



**Operating Manual** 

# Turbine Meter TME400-VM (..-VMF)

Stand: 2021 July 1st 80 Version: Firmware: 1.08



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You can register your product on our website at <u>https://www.rmg.com/en/help/device-registration</u>. By this you are helping us to improve our support

Translation of the	The manual TME400VMF_manual_en_08 of
original document	2021 July 1st for the TME400-VM and TME400-VMF
	turbine meters is a translation of the the original Ger- man document <b>TME400VMF_manual_de_08</b> .

**Note** Unfortunately, paper is not updated automatically, whereas technical development continuously advances. Therefore, we reserve the right to make technical changes in regard to the representations and specifications of these operating instructions. The latest version of this manual (and other devices) can be downloaded at your convenience from our Internet page:

#### www.rmg.com.

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# TABLE OF CONTENTS

1. INTRODUCTION1
1.1. STRUCTURE OF THE MANUAL1
1.2. PURPOSE OF THE MANUAL
1.2.1. ABBREVIATIONS
1.2.2. SYMBOLS
1.2.3. STRUCTURE OF NOTICES
1.2.4. WORKING WITH THE DEVICE
1.2.4.1. SAFETY NOTICES DANGER, WARNING, CAUTION AND NOTE4
1.2.4.2. DANGERS DURING COMMISSIONING
1.2.4.3. DANGERS DURING MAINTENANCE AND REPAIR
1.2.4.4. QUALIFICATION OF PERSONNEL9
1.2.5. RISK ASSESSMENT AND MINIMIZATION
1.2.6. APPLICABILITY OF THE MANUAL
1.2.6.1. DANGER DURING OPERATION12
1.2.6.2. DANGERS OF OPERATION IN EX AREAS
1.2.6.3. RESPONSIBILITY OF THE OPERATOR
1.2.7. TRANSPORT
1.2.8. SCOPE OF DELIVERY
1.2.9. DISPOSAL OF PACKAGING MATERIAL
1.2.10. STORAGE
1.3. OVERVIEW OF VERSIONS
1.3.1. DESCRIPTION
1.3.2. DEVICE FEATURES
1.3.3. POWER SUPPLY
1.3.4. AREA OF APPLICATION
1.3.4.1. INSTALLATION AND MOUNTING POSITION
1.3.4.2. TEMPERATURE RANGES
1.3.5. USE OF GAS METERS FOR DIFFERENT GASES
1.3.5.1. SUITABILITY AND COMPATIBILITY FOR NATURAL GAS CONTAINING H <sub>2</sub> 20
1.4. AREAS OF APPLICATION
1.4.1. WORKING PRINCIPLE OF THE TME400

#### CONTENTS

Ш

.....

# RMG<sup>•</sup>

1.4.2. INTEGRATING THE TURBINE METER INTO THE PIPELINE
1.4.2.1. SEALS
1.4.2.2. SCREWS
1.4.2.3. METER HOUSING MATERIAL
1.4.2.4. INSTALLATION
1.4.2.5. THRESHOLD VALUES
1.4.2.6. TECHNICAL GUIDELINE G13
1.4.2.7. STANDARDS / GUIDELINES
1.4.2.8. MEASURING RANGES
1.4.2.9. MEASURING ACCURACY
1.4.2.10. PRESSURE LOSS
1.4.2.11. PUTTING THE DEVICE INTO OPERATION
1.4.2.12. MAINTENANCE / LUBRICATION
2. INSTALLATION
2.1. ELECTRICAL CONNECTIONS
3. TME40044
3.1. DISPLAY FIELD
3.1.1. DISPLAY TEST45
3.1.2. RESET45
3.1.3. BOOTING UP45
3.1.4. BATTERY REPLACEMENT48
4. OPERATION
4.1. OPERATION CONCEPT
4.1.1. COORDINATE SYSTEM
4.1.2. DISPLAY AND COORDINATE SYSTEM53
4.1.2.DISPLAY AND COORDINATE SYSTEM
4.1.3. PARAMETER PROTECTION
4.1.3. PARAMETER PROTECTION
4.1.3.PARAMETER PROTECTION
4.1.3.PARAMETER PROTECTION

# RMG

#### Contents

.....

4.3	.3.1.	1. VOLUME / METERS		
4.3	.3.2.	FLOW RATE60		
4.3	.3.3.	CURRENT OUTPUT61		
4.3	.3.4.	ERROR / TYPE PLATE62		
4.3	.3.5.	RS-485 INTERFACE63		
4.3	.3.6.	ARCHIVE64		
4.3	.3.7.	SETTINGS		
4.4	. S	PECIAL SETTINGS		
4.4	.1.	CONFIGURATION OF THE CURRENT OUTPUT		
4.5	. R	MGVIEW™ <sup>E</sup>		
5.	TEC	CHNICAL DATA		
5.1	.1.	DEVICE TYPES		
5.1	.2.	INPUTS		
5.1	.2.1.	POWER SUPPLY		
5.1	.2.2.	PULSE IN MEASURING INPUTS (SENSOR 1 / 2)72		
5.1		OUTPUTS		
5.1	-	DATA INTERFACE		
5.1		CURRENT LOOP CONNECTION		
5.1		CABLE		
5.1	-	CABLE CONNECTION		
5.1		GROUND		
5.1		VERVIEW OF MATERIALS IN USE		
		ROR MESSAGES		
0.				
		DIX		
A _	_	DBUS		
В	-	RUCTURE OF THE ARCHIVES		
	81 82	ARCHIVE SIZE		
	sz 32.1	PARAMETER ARCHIVES		
_	32.2	EVENT ARCHIVES		
	32.3	MEASURED VALUES ARCHIVES		
	33	CALCULATION OF THE STORAGE SIZE		
_	34	ARCHIVE HEADER		
_	,- 85	READING THE ARCHIVE DATA VIA MODBUS		

.....

III

#### CONTENTS

IV

.....

# RMG

С	DIMENSIONS	97
D	MEASURING RANGES FOR TME 400-VMF/ TME 400-VCF	102
Е	TYPE PLATE	103
F	SEAL DIAGRAMS	105
G	LATER INSTALLATION OF THE POWER MODULE	106
н	SPARE PARTS AND ACCESSORIES	108
Т	CERTIFICATES AND APPROVALS	109

# **1** Introduction

# 1.1 Structure of the manual

The introduction of this manual comprises two parts. The first part lists general specifications; the symbols used in the manual and the structure of notices are presented and a risk assessment is provided. The differences between the TME400-VM and TME400-VMF turbine meters are explained. If there is no explicit reference to differences, the TME400 is superordinate for both versions of the turbine meter.

### Note

This manual refers to the TME400-VM and TME400-VMF instead of the complete turbine meter.

In addition, the first part includes specifications for the transport and storage of the TME400. The second part of the introduction describes the features and areas of application of the TME400; basic standards are listed and the pressure and temperature ranges in which the TME400 can and may be used are pre-adjusted.

The second chapter describes the electrical and mechanical commissioning of the TME400. An explanation of how to achieve the reliable commissioning of the meter and high precision is provided.

The third chapter explains the displays of the TME400. It explains resetting, booting and replacement of the battery.

The settings of the TME400 are explained in chapter four. In particular, all adjustable parameters are provided there with some explanations.

The fifth chapter summarizes the technical data and the sixth chapter provides a list of error messages.

The appendix provides details about the Modbus, measurements, type plate and seal plans. Then the certificates and approvals are listed.



# **1.2** Purpose of the manual

This manual provides information that is necessary for fault-free and safe operation.

The TME400 was designed and produced according to the state of the art and generally recognized safety standards and directives. However, its use can entail dangers that are avoidable by complying with this manual. The device must only be used as intended and in technically sound condition.

## A Warning

Unintended use voids all warranty claims and the TME400 can also lose its approvals.

# 1.2.1 Abbreviations

The following abbreviations are used:

TME400-VM	The TME400-VM is a turbine meter which is used for non-custody-transfer volume measurement ( $\underline{V}$ olume $\underline{M}$ easurement) of the operating volume of non-aggressive gases and combustion fuels is used.
TME400-VMF	The TME400-VMF is a turbine gas meter that is used in custody- transfer applications ( <u>F</u> iscally). The designation TME400-VMF comprises all turbine meters.
TME400-VC	The TME400-VC also enables calculation of the standard volume flow ( $\underline{V}$ olume $\underline{C}$ orrector) from the operating volume flow in non-custody-transfer applications.
TME400-VCF	The TME400-VCF is used in custody-transfer applications ( <u>F</u> iscally). In addition to the turbine meter, the TME400-VCF designation also includes the volume corrector.

### Note

This manual only describes the TME400-VM and TME400-VMF.

MessEG	Measurement and Calibration Act Law on the marketing and provision of measuring devices in the market, their use and calibration, valid since 1/1/2015
MessEV	Measurement and Calibration Regulation Regulation on the marketing and provision of measuring devices in the market and on their use and calibration; 12/11/2014
MID	Measurement Instruments Directive
РТВ	Physikalisch-Technische Bundesanstalt [German National Test Authority]
Vo	original meter reading (Volume) of a mechanical counter
approx.	approximately
max.	maximum
min.	minimum

# 1.2.2 Symbols

The following symbols are used:

1, 2,	Identifies steps for work tasks

# 1.2.3 Structure of notices

The following notices are used:

# A Danger

This warning notice informs you of imminently threatening dangers that can arise due to misuse/operator error. If these situations are not avoided, death or severe injuries can occur.

#### 1 Introduction



#### A Warning

This warning notice informs you of potentially dangerous situations that can arise due to misuse/operator error. If these situations are not avoided, minor injuries can occur.

## Caution

This notice informs you of potentially dangerous situations that can arise due to misuse/operator error. If these situations are not avoided, damage to the device or nearby property can occur.

### Note

4

This notice informs you of potentially dangerous situations that can arise due to misuse/operator error. If these situations are not avoided, damage to the device or nearby property can occur.

This notice can provide you with helpful tips to make your work easier. This notice also provides you with further information about the device or the work process in order to prevent operator error.

#### 1.2.4 Working with the device

**1.2.4.1** Safety notices Danger, Warning, Caution and Note

	Danger			
All of	the following sa	fety notices mu	ust be observed!	

Disregard of the safety notices can result in danger to the life and limb or environmental and property damage.

Bear in mind that the safety warnings in this manual and on the device cannot cover all potentially dangerous situations, because the interaction of various conditions can be impossible to foresee. Merely following the instructions may not suffice for correct operation. Always remain attentive and consider potential consequences.



- Read this operating manual and especially the following safety notices carefully before working with the device for the first time.
- Warnings are provided in the operating manual for unavoidable residual risks for users, third parties, equipment or other property. The safety instructions used in this manual do not refer to unavoidable residual risks.
- Only operate the device in fault-free condition and in observance of the operating manual.
- Compliance with local statutory accident prevention, installation and assembly regulations is also mandatory.

## Caution

All notices in the manual must be observed. Use of the TME400 is only permitted in accordance with the specifications in the operating manual. RMG assumes no liability for damages arising due to disregard of the operating manual.

# A Danger

Service and maintenance tasks or repairs that are not described in the operating manual must not be carried out without prior consultation with the manufacturer. The device must not be opened forcefully.

# **A** Caution

The TME400 is approved for custody-transfer applications. For this purpose, it is sealed before deliver and settings specified by the approval authority are locked. These seals, software or hardware locks must not be damaged, destroyed or removed!

In this case, the TME400 loses its official certification!

The TME400 can only be approved for officially certified operation after a renewed inspection by an officially recognized inspection authority or calibration officials and an additional inspection of additional settings. The calibration official must re-apply the seals after the inspection. 5



Observe the following, in particular:

- Changes to the TME400 are not permitted.
- The technical specifications must be observed and followed for safe operation. Performance limits must not be exceeded (*chapter 5 Technical data*)
- For safe operation, the TME400 must only be used in the scope of the intended use (*chapter 1.3 Overview of versions*).
- The TME400 complies with current standards and regulations. However, danger can arise with misuse.

#### 1.2.4.2 Dangers during commissioning

Initial commissioning The initial commissioning must only be carried out by specially trained personnel (training by RMG) or RMG service personnel.

### Note

An acceptance test certificate must be created during the commissioning. This, the operating manual and the EU Declaration of Conformity must be stored so that they are always readily available.

All sharp edges on the device were removed, insofar as possible. However, personal protective equipment provided by the operator must be worn during all work.

#### 🛕 Danger

Install the device as specified in the operating manual. If the device is not installed as specified in the operating manual, there may be a risk that adequate explosion protection is not provided.

The explosion protection is lost!

# RMG

# 🛦 Danger

Inadequately qualified persons working on the equipment are unable to correctly estimate dangers. Explosions can be triggered. Only work on the equipment if you have the appropriate qualifications.

Components can be damaged if you do not use suitable tools and materials. Use tools that are recommended for the respective work in the operating manual.

Mechanical installation	Mechanical installation must only be performed by appro priately qualified technicians.
Electrical installation	Installation on electrical components must only be carried out by qualified electricians.
Mechanical and/or electrical installation	These qualified personnel require training specifically for work in hazardous areas. Qualified personnel are persons who have training / education in accordance with <b>DIN</b> <b>VDE 0105</b> , <b>IEC 364</b> or <b>comparable standards</b> .

# 🛦 Danger

Installation and removal of the TME400 must only take place in an explosionfree, pressure-free atmosphere. The descriptions in the operating manual must be observed. In general, it is recommended that the replacement should only be carried out by RMG Service.

A leak test must be carried out after work on pressurized components.

All of the above points also apply to repair and maintenance tasks and in general when opening the meter is necessary.

Flange fastening elements, fastening screws, screw couplings and check valves, the oil supply, pressure relief connections, valves, HF pulse generators, protective pipes and swivel adapters must <u>not</u> be loosened during operation.

### 1.2.4.3 Dangers during maintenance and repair

Operating personnel	The operating personnel use and operate the device in the scope of the intended use.
Maintenance personnel	Work on the device must only be carried out by qualified personnel who can carry out the respective tasks on the



basis of their technical training, experience and familiarity with the applicable standards and requirements. These qualified personnel are familiar with the applicable statutory regulations for accident prevention and can independently recognize and avoid potential dangers.

Maintenance and cleaning Maintenance and cleaning must only be performed by appropriately qualified technicians.

#### 🛕 Danger

Inadequately qualified persons working on the equipment are unable to correctly estimate dangers. Explosions can be triggered. If work on live equipment must be conducted in hazardous areas, sparks that are created can trigger an explosion.

#### 🛦 Danger

The device can be damaged if it is not cleaned as specified in the operating manual. Only clean the device as specified in the operating manual.

Components can be damaged if you do not use suitable tools. The explosion protection is lost.

Only clean the device with a damp cloth!

#### \Lambda Danger

The TME400 must only be used as intended! (*Chapter 1.3 Overview of versions*). Prevent use of the TME400 as a potential climbing aid or use of attachments of the TME400 as potential handles!

#### 1.2.4.4 Qualification of personnel

#### Note

In general, the following is recommended for all persons working with or on the TME400:

- Training / education for work in hazardous areas.
- The capacity to be able to correctly estimate dangers and risks when working with the TME400 and all connected devices. Possible dangers include components that are under pressure and consequences of incorrect installation.
- Recognition of dangers that can arise from the flow medium that is used.
- Training / education by RMG for work with gas measuring devices.
- Education / instruction in all national standards and directives to be complied with for the work to be carried out on the device.

### 1.2.5 Risk assessment and minimization

According to assessment by qualified employees of RMG, the TME400 is subject to risks during its use. Risks can arise, for example, due to high pressures and occasionally due to pressures that are too low. Work outside of the permissible temperature range can also lead to dangers. Impermissible current and voltage values can trigger explosions in hazardous areas. The risk assessment requires an emptying and ventilation of the pipeline for connection with installation and removal of a turbine. Then and only then is it assured that there is not an hazardous gas mixture in the pipeline. Naturally, work must only be carried out by trained personnel (see *chapter 1.2.4.4 Qualification of personnel*), who are also trained to recognize suitable tools and use them exclusively. The risks were summarized alongside development and measures were taken to minimize these risks.

#### Measures for risk minimization:

- All pressurized parts are designed in accordance with AD 2000 rules and regulations, Pressure Equipment Directive, Annex 1
- The complete pressure design has been inspected by TÜV Hessen
- All pressurized parts have been manufactured with a material certificate; there is an uninterrupted change of batch tracing of pressurized components
- The mechanical properties of all relevant pressurized components have been subjected to tension tests, notch impact bending tests and hardness tests

Manual TME400-VMF · EN08 · July, 1st 2021

- Non-destructive testing was also carried out: X-ray and ultrasonic inspection of the meter housing for defective points in material, surface crack testing with magnetic powder and a color penetration process
- Strength tests for components were conducted at 1.5 times the nominal pressure for the pressure testing; the leak testing for the assembly was conducted at 1.1. times the nominal pressure. Certificates were issued for successfully passed tests
- The maximum operating pressure and the permissible temperature range are specified on the type plate of the device. Operation of the device is only permitted within these specified ranges.
- A maximal temperature difference of  $\Delta T \le 100^{\circ}$ K between the inside and outside of the TME400 must be respected.
- Additional external forces and torques were not taken into account in the pressure dimensioning.
- In the event that the pressure equipment is to be marketed and put into operation as an assembly within the meaning of the Pressure Equipment-Directive, an examination of the assembly must be provided at the latest during the final and pressure tests.

Otherwise, the commissioning inspector must explicitly point out that a test of the equipment location with safety function still has to be performed at the installation site.

# RMG

### 🛕 🛛 Danger

The following applies for work in hazardous areas (all zones):

- The pulse generators of the turbine meter must be connected to intrinsically safe power circuit only.
- Only tools that are approved for Ex Zone 1 are permitted for maintenance and repair tasks.
- Otherwise, work must only be carried out when there is not an explosive atmosphere.
- The risk of ignition due to impact or friction must be avoided.
- Work on devices which are used in hazardous areas must be carried out by qualified electrical engineers with special capabilities for work in hazardous areas.
- The wiring / installation in hazardous areas must only be carried out by trained personnel in accordance with EN60079-14 and in observance of national regulations.
- Qualified persons must satisfy the definitions in accordance with DIN EN 0105 or IEC 364 or directly comparable standards.
- If one or more power circuits are used, it must be ensured that the permissible limit values according to the EC type approval certificate are not exceeded when choosing the cables.
- Every Ex signal circuit must be routed with a dedicated cable which must be guided through the appropriate PG screw coupling.
- Permanent installation of the intrinsically safe cable is mandatory.

# 🛕 🛛 Danger

In addition, the following applies for work in hazardous areas (all zones):

- Only trained and instructed personnel are permitted. Work on the measuring system must only be carried out from qualified persons and inspected by responsible qualified supervisors.
- Qualified persons have been authorized by the person responsible for safety of personnel to carrying out such work on the basis of their training, experience or instruction and familiarity with applicable standards, provisions, accident prevention regulations and system conditions. It is essential that these persons are able to recognize and avoid potential dangers in good time.



## **1.2.6** Applicability of the manual

This manual describes the TME400. TME400 is generally only part of a complete system. The manuals of the other components of the system must be observed. If you find contradictory instructions, contact RMG and/or the manufacturers of the other components.

#### Note

12

Ensure that the power data of the current connection matches the specifications on the type plate. Ensure that the limit values specified in the conformity certificate (see appendix) for the devices to be connected are not exceeded.

Observe any applicable national regulations in the country of use. Use cable that is appropriate for the cable fittings.

#### A Danger

Only work on the equipment if you have the appropriate training and qualifications.

Attention: Risk of destruction due to body electricity, e.g. due to the rubbing of clothing.

#### 1.2.6.1 Danger during operation

Observe the specifications of the system manufacturer and/or system operator.

#### 1.2.6.2 Dangers of operation in EX areas

Only operate the device in fault-free and complete condition. If you make technical changes to the device, safe operation can no longer be guaranteed.

#### 🛦 Danger

Only use the device in its original condition. The TME400 is permitted for operation in Ex Protection Zone 1, but only within the permissible temperature range (*chapter 1.3.4.2 Temperature* ranges).



#### 1.2.6.3 Responsibility of the operator

As the operator, you must ensure that only adequately qualified personnel work on the device. Ensure that all employees who work with the device have read and understood this manual. You are also obligated to train personnel regularly and inform them of the dangers. Ensure that all work on the device is carried out exclusively by qualified persons and inspected by responsible qualified supervisors. The responsibilities for installation, operation, fault rectification, maintenance and cleaning must be clearly regulated. Instruct your personnel with regard to the risks involved with working with the device.

## 1.2.7 Transport

The device is packaged specific to the transport requirements for each customer. Ensure safe packaging that absorbs light impact and vibrations is used for any further transport. Nevertheless, inform the transport company that all types of impact and vibrations should be avoided during transport.



# 🛕 Warning

#### **Risk of injury during transport**

Any foot screws must be mounted if they are provided as a transport safeguard to prevent rolling and tipping. Additional measures must be taken to ensure that impermissible rolling and tipping are prevented.

Only use the provided lifting eyes / ring screws to lift the meter. Please observe the relevant permissible loads for the lifting equipment. Prior to lifting, ensure that the load is securely fastened. Do not stand under suspended loads.

The device can slip, topple over or fall down when being lifted and set down. The device can fall over if the bearing capacity of the lifting equipment is disregarded. There is a risk of severe injury for nearby persons.

If the device is delivered on a Euro pallet, the device can be transported on the pallet using a pallet truck or forklift.

The gas meters and accessories must be protected from jarring and vibrations during transport.

The gas meters or any inlet/outlet pieces have a flange as an end piece. The flanges are sealed with a protective sticker or fitted with a plastic dummy plug. The protective stickers and/or dummy plugs must be removed without leaving any residue prior to installation in the pipeline. Residue from this film changes the flow and causes measuring errors!

This protection must be re-applied to the flanges for transport or storage of the device.

# 1.2.8 Scope of delivery

The scope of delivery can differ depending on the optional orders. The following is "normally" included in the scope of delivery:

Part	Quan- tity
TME400-VM (or TME400-VMF) turbine meter	1
1 Lubricating oil bottle	Op- tional
Lubricating instructions	1
Manual	1

14

# RMG

15

Test log	1
Calibration certificate	1
Material test certificate	1
Strength test certificate 3.1.	Op- tional

# **1.2.9** Disposal of packaging material

Dispose of the material in an environmentally friendly manner in accordance with national standards and directives.

# 1.2.10 Storage

Avoid extended periods of storage. After storage, inspect the device for damage and test for correct function. Contact the RMG service department to arrange for inspection of the device after a storage period of longer than one year. For this purpose, return the device to RMG.

#### Note

Storage must take place in a dry and protected room.

It must be ensured that all open pipes are sealed.



# 1.3 Overview of versions

# 1.3.1 Description

The **TME400-VM** is a turbine meter which is used for volume measurement of the operating volume of non-aggressive gases and burnable gas. The operating volume flow is determined based on the turbine speed, which is scanned by means of a Wiegand or Reed sensor element and then added together in internal archives. The result is registered in an electronic meter.

There are a high-frequency (HF) and a low-frequency (LF) output, where the HF output is preferably used as a flow sensor for control tasks and remote transmission. In addition to these outputs, the TME400 VM has a serial RS 485 interface for digital data readings and parameterization. The TME400-VM is used in **non-custody-transfer** applications.

The **TME400-VMF** (MID) is the turbine meter for custody-transfer applications and has an equivalent function and operating method to the TME400-VM. The essential difference is the 2-channel measuring head version. It is used in **custody-transfer applications**.

### **1.3.2** Device features

#### TME400-VM

- Non-custody-transfer measurements
- Electronic meter
- Alarm output
- Optionally available in a version with remote meter (distance from meter head to meter: 10 m; see appendix C Dimensions)
- 2x pulse inputs selectable for Reed, Wiegand and external pulse transmitters (remote meters)
- 1x contact input
- 1x HF output
  - (input pulse of pulse input 1 is output with defined pulse width of 1 ms)
- 1x LF output with defined pulse width (20 ms, 125 ms or 250 ms)
- 1x RS485 with external power supply
- 1x optional power module
- Power supply via 3.6V lithium cell or an external power supply which is assigned to the RS485 interface (supply via power module alone is not adequate and a battery is required for support)
- Archive memory for events, parameters, measurements



#### TME400-VMF

In addition to the features of the TME400 VM, this version can be used for custody-transfer applications.

## 1.3.3 Power supply

#### Battery-operated device

The TME400 is equipped with a replaceable 3.6 V lithium battery. The device is designed for continuous operation for approximately 10 years. To achieve this, the devices may be operated for a maximum of 15 minutes per day with input pulses of 1 Hz.

#### Battery-operated device with additional external power supply

An electric supply of the TME400 via the 4-20mA current loop reduces the power consumption from the batterie and typically extends the service life of the battery to more than 12 years.

If the TME400 is additionally electrical powered by the RS485 interface, the service life of the battery is typically extended to clearly more than 12 years.

#### **Battery replacement indicator**

The remaining battery life is determined by means of an internal calculation. An indicator in the display appears when it is time to replace the battery. Battery replacement is described in *chapter 3.1.4 Battery replacement*. In parameter G20 *Date of last battery change* the date of the last battery change is displayed (see *chapter 4.3.3 Coordinates in context*).

#### Note

In case of a loss of the external power supply, the TME400 is supplied by the buffer battery. The battery symbol is blinking in this case.

# 1.3.4 Area of application

The TME400 is approved for use in hazardous areas with the following mark:



II 2G Ex ia IIC T4 Gb



The EC type approval certificate is:

#### TÜV 17 ATEX 207566 X IECEx TUN 18.0009 X

The corresponding conformity certificates are provided in the annex. The RMG contact information is provided on the second and last page.

#### 1.3.4.1 Installation and mounting position

The TME400-VM and TME400-VMF can be supplied with DIN and ANSI connections. Up to nominal diameter DN 200, the installation position of the turbine meter with permanent lubrication can be selected as required. From nominal diameter DN 250, the meter must be installed in the ordered installation position. It must also be ensured that the filling opening of the lubrication faces upwards.

#### 1.3.4.2 Temperature ranges

The turbine meter TME400 in standard version is approved for the following temperature ranges.

Temperature ranges	
Medium temperature	-25°C to +55°C
According to ATEX (Tamb)	-25°C to +55°C (II 2G Ex ia IIC T4)
According to PED 2014/68/EU	-20°C to +80°C (spheroidal graphite iron) -40°C to +80°C (cast steel) -40°C to +80°C (stainless steel) -10°C to +80°C (welded version and round steel material)
Pressure safety for DN25 according to sound engineering practice, see PED 2014/68/EU, sec. 4, subsec. 3	-40°C to +60°C (aluminum)

Lower temperature limits are available on request with the welded version and round steel material.

## A Caution

#### Direct solar radiation must be avoided.

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# Note

1.3.5

If different temperature ranges apply simultaneously, the smallest specified range applies for the overall system. This is also marked on the type plate.

Use of gas meters for different gases

19

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Gas	Symbol	Tight- ness at 0°C and 1.013 bar	Meter housing	Comments
Natural gas		0.8	Standard	
City gas			Standard	
Methane	CH4	0.72	Standard	
Ethane	C <sub>2</sub> H <sub>6</sub>	1.36	Standard	
Propane	СзН8	2.02	Standard	
Butane	C4H10	2.70	Standard	
Air		1.29	Standard	
Argon	Ar	1.78	Standard	
Helium	He	0.18	Standard	
Carbon dioxide (dry)	CO <sub>2</sub>	1.98	Standard	
Nitrogen	N2	1.25	Standard	
Hydrogen	H2	0.09	Standard	up to 100% Generally, a reduced meas- uring range
Ethylene (gaseous)	C <sub>2</sub> H <sub>4</sub>	1.26	Special	Special version (also for hu-
Biogas			Special	mid gases):
Sour gas			Special	Teflon coating, special lubri-
Digester gas / sewage gas			Special	cation, special material, etc.
Sulfur dioxide	SO <sub>2</sub>	2.93	Special	

# The components of the gases must be within the concentration limits according to EN 437:2009 for test gases. Safe operation is guaranteed with these specified gases.

Other gases on request.



#### **1.3.5.1** Suitability and compatibility for natural gas containing H2

The TME400 can be used in hydrogen-containing natural gas up to pure hydrogen. There are no safety-related concerns for this use.

Χ.		
Δ.	ОТ	

In accordance with the German TR-G19 – the TME400 is suitable and approved for use in custody transfer applications – in natural gases with a maximum hydrogen content of 10 mol-%, with the accuracy specified in *chapter 1.4.2.9 Measuring accuracy*.

Since there are currently no certified test rigs in Germany to calibrate meters with higher hydrogen-containing gases, an accuracy above 10 mol-% cannot be tested or certified.

Not custody transfer measurements are of course possible in natural gases with a hydrogen content above 10 mol%. However, a reduced measuring range must be taken into account if applicable. Please contact RMG for further information.

# **1.4** Areas of application

The following chapter provides handling instructions for the TME400 turbine meter for the purpose of safe and reliable operation of the device.

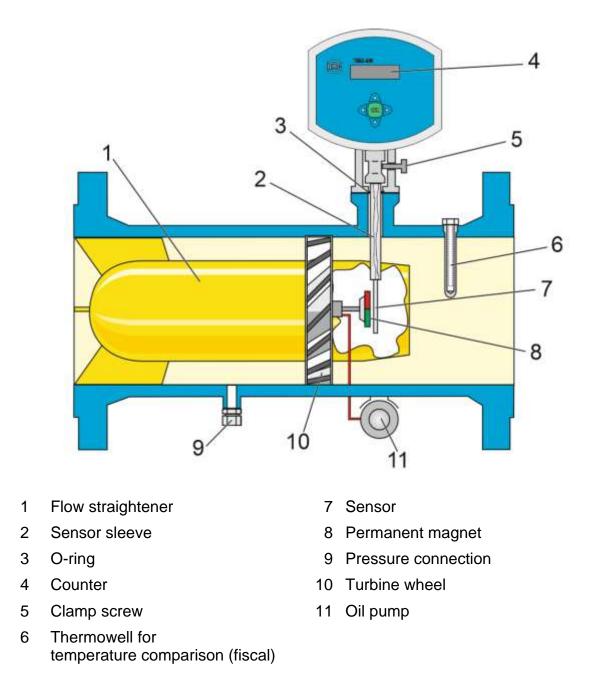
#### Note

Some of the settings described below must not be made until you have read the explanations in *chapter* 4 Operation.

# 1.4.1 Working principle of the TME400

The working principle of a mechanical turbine meter is based on the measurement of the gas velocity of the flowing gas which powers a turbine wheel. The speed of the turbine within the measuring range  $(Q_{min} - Q_{max})$  is approximately proportional to the mean gas velocity and thus the flow rate. The number of rotations, therefore, is a measurement for the gas volume flowing through.





#### Figure 1: Turbine meter sectional drawing

There is a permanent magnet on the end disc of the turbine shaft which induces a voltage pulse in the Wiegand sensor with every rotation. This pulse is supplied to the measuring unit of the meter head, which detects the operating volume flow directly as a main totalizer and determines the gas volume flowing through the meter by adding up the pulses and division by the meter factor (number of pulses per m<sup>3</sup>). This operating volume is shown in the display of the TME400.



#### Note

22

The unchanged signal frequency of the sensor element is output at the HF output.

The LF output transmits this HF frequency with a variable scaling factor (*chapter* 4.3.3.1 Volume / Meters).

### 1.4.2 Integrating the turbine meter into the pipeline

Turbine meters from RMG are equipped with connecting flanges. For a secure connection, the connection dimensions of the flanges of the pipelines to be connected must match the connection dimensions of the flanges of the device.

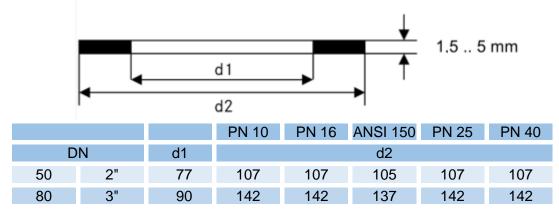
- ANSI pressure levels: flange connection dimensions correspond to the standard ASME B 16.5.
- DIN pressure levels: flange connection dimensions correspond to the standard DIN EN 1092.

#### 1.4.2.1 Seals

	Flat seals: Grooved seals:	$k_0 \ge K_D = 20 \ge b_D   k_1 = 1.3 \ge b_D [N/mm]$ $k_0 \ge K_D = 15 \ge b_D   k_1 = 1.1 \ge b_D [N/mm]$
	Spiral seals:	$k_0 \times K_D = 10 \times b_D   k_1 = 1.4 \times b_D [N/mm]$ $k_0 \times K_D = 50 \times b_D   k_1 = 1.4 \times b_D [N/mm]$
٠	Octagonal ring-joint seal:	$K_D = 480 \text{ N/mm}^2$

Refer to the tables below for the recommended dimensions.

Flat seals (DIN 2690 / EN 12560-1 Form IBC)

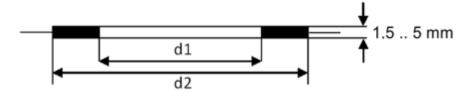




1 Introduction

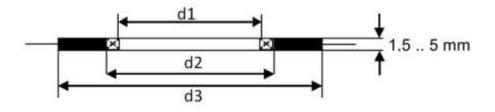
100	4"	115	162	162	175	168	168
150	6"	169	218	218	222	225	225
200	8"	220	273	273	279	285	292
250	10"	274	328	330	340	342	353
300	12"	325	378	385	410	402	418
400	16"	420	490	497	514	515	547
500	20"	520	595	618	607	625	628
600	24"	620	695	735	718	730	745

Grooved seals (EN 12560-6 with centering ring)



		ANSI 300	ANSI 600	PN	64
[	ON	d1	d2	d1	d2
50	2"	69.8	88.9	65	87
80	3"	98.4	123.8	95	121
100	4"	123.8	154.0	118	144
150	6"	177.8	212.7	170	204
200	8"	228.6	266.7	220	258
250	10"	282.6	320.7	270	315
300	12"	339.7	377.8	320	365
400	16"	422.3	466.7	426	474
500	20"	530.2	581.0	530	578
600	24"	631.8	682.6	630	680

#### Spiral seals (EN 12560-2 with centering ring)



23

.....

#### 1 Introduction



				ANS	I 300		PN	64		ANS	l 600
	D	N	d1	d2	d3	d1	d2	d3		d1	d2
	50	2"	51	69.9	85.9	54	66	84	51	69.9	85.9
	80	3"	81	101.6	120.7	86	95	119	81	101.6	120.7
	100	4"	106.4	127.0	149.4	108	120	144	106.4	120.7	149.4
24	150	6"	157.2	182.6	209.6	162	174	200	157.2	174.8	209.6
	200	8"	215.9	233.4	263.7	213	225	257	215.9	225.6	263.7
	250	10"	268.3	287.3	317.5	267	279	315	268.3	274.6	317.5
	300	12"	317.5	339.9	374.7	318	330	366	317.5	327.2	374.7
	400	16"	400	422.4	463.6	414	426	466	400	412.8	463.6
	500	20"	500	525.5	577.9	518	530	574	500	520.7	577.9
	600	24"	603.3	628.7	685.8	618	630	674	603.3	628.7	685.8

#### For flanges according to ASME to be observed:

- Gasket type:

flat gasket tanged sheet metal/graphite or similar - Gasket dimensions: according to ASME B16.21

- Seal data:
  - design seat tension
    - $Y_{max} = 45$  MPa, sealing factor  $m_{max} = 2.5$

#### Note

When flange seals which protrude into the pipeline are used for turbine meters, the measuring accuracy can be influenced negatively. Ensure that the flange seals do not protrude beyond the seal surfaces into the pipeline.

#### Δ Danger

Gas escape due to incorrect seal

If incorrect flange seals are used for the assembly of turbines, an explosive gas mixture can form due to leaks.

Danger of poisoning and explosion!

In addition, the stress on the flange is increased to an impermissible level when tightening the thread bolts.

Ensure secure fastening/attachment of the TME400 during assembly in order to avoid crushing. Ensure that you keep your fingers (or other body parts) away from these openings and gaps when pulling the flanges together.

# RMG

#### 1.4.2.2 Screws

	Temperature ranges for screws and nuts						
	-10°C to +80°C	-40°C to +80°C					
Pressure levels		Option 1	Option 2	Option 3			
up to and including 40 bar	Screws according to DIN EN ISO 4014 in material 5.6 Nuts according to DIN EN ISO 4032 in material 5-2	Screws according to DIN EN ISO 4014 in material 25CrMo4, Nuts according to DIN EN ISO 4032 in material 25CrMo4					
40 bar or higher	Threaded bolts according to ANSI B1.1 material ASTM A 193 degree B7, Nuts according to ANSI B1.1 material ASTM A 194 degree 2H,	Threaded bolts according to ANSI B1.1 material ASTM A 320 degree L7, Nuts according to ANSI B1.1 material ASTM A 320 degree L7,	Threaded bolts according to ANSI B1.1 material 42CrMo4 Nuts according to ANSI B1.1 material 42CrMo4	Reduced shaft screws according to DIN 2510 material 25CrMo4, Nuts according to DIN 2510 material 25CrMo4			

For flanges according to ASME to be observed > -10°C:

Screw material SA.193 B7/B7M according to ASTM A193 Grade B7 or comparable materials.

# Note

Reduced shaft screws must only be used for devices in the area of application of the Pressure Equipment Directive.

The durability of the flange connection was verified using the screws listed in this chapter in combination with the seals listed in the previous chapter with the following maximum material characteristic data according to AD200 rules and regulations. Other screw/flange variants were not tested.

Malfunctions can occur with incorrect seals.

#### 1.4.2.3 Meter housing material

Cast steel or round steel material, depending on the pressure level and nominal diameter. Aluminum or stainless steel for the screw-type versions.



#### 1.4.2.4 Installation

#### Note

Installations disturbing the gas flow directly upstream of the turbine meter must be avoided

(see DVGW guideline G 492 II and PTGB guideline G 13).

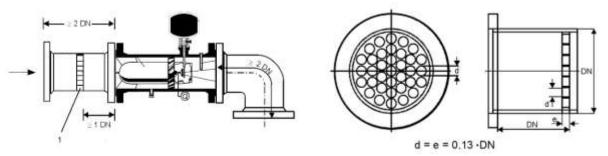
An inlet pipe of at least 2 x DN is required upstream from the turbine meter TME400. The inlet pipe must be designed as a straight pipe section with the same nominal diameter as the meter. With heavy upstream pertubations, installation of straighteners is recommended (refer to the table on the next page). A pipe or bend with the nominal diameter of the meter having a total length of 2 x DN must be arranged downstream from the meter.

Temperature measuring devices must be installed at a distance of at least 1 x DN or at least 300 mm with nominal diameters  $\ge$  DN 300.

If there is pertubation (e.g. a gas pressure control device) upstream from the inlet pipe, a perforated plate straightener is also necessary. Perforated plate straightener according to ISO 5167-1 or the type RMG LP-35, which cause a pressure loss by a factor of 2.5 in comparison with the standard straightener, can be used.

Recommended installation with straightener

Perforated plate straightener LP 35



1 Perforated plate straightener

• The opening angle of the reducing or expansion pieces which are installed upstream from the TME400 turbine meter must not be more than 30°.

#### Note

If necessary, a screen must be installed before the inlet pipe of the meter for protection of the turbine meter from foreign objects which may be present in the gas flow. The screen can be, for example, a perforated plate/filter of  $\emptyset$  0.15 mm.

# RMG

# 🛦 Danger

Protect the turbine meter from damage caused by high pressure changes fluctuations in the flow, e.g. if the downstream pipeline system is filled or blown off.

# A Danger

Welding on the line must only take place at a safe distance from the meter. Extreme temperatures in the line near the meter can cause permanent damage to the meter.

# 🛦 Danger

Establish all electrical connections between meters and amplifiers or flow computers as specified in the installation manual. Ensure that the connections are intrinsically safe.

# **A** Caution

Liquids remaining in the line after hydrostatic testing can damage internal parts of the meter.

If hydrostatic testing is not possible, the turbine meter must be replaced with a pipe section. Ensure that there is no liquid remaining in the line above the meter after the hydrostatic testing.

# 1.4.2.5 Threshold values

The following threshold values are recommended for maximum durability and the highest measuring accuracy:



Note	
Maximum overload	< 20% above Q <sub>max</sub> , short-term (< 30 sec)
Maximum flow rate changes and/or impact loads	< 0.01.Qmax/sec = 1% of Qmax/sec e.g. start-up 0 - 100%: > 100 sec
Maximum pressure change:	< 0.1 bar/sec
Maximum flow pulsation:	< 5%
Particle size in the gas flow:	< 5 µm
Lubrication:	Refer to lubrication chapter Intervals depend on the status of the gas (condensate, rust, dust)
Vibration / mech. vibration:	< 1 mm/sec (vibration speed)

These measures must be determined and checked during commissioning, before filling, during the start-up and run-in phase of the meter and evaluated, in particularly with simultaneous occurrence of multiple of these threshold values. Intervention in the system for improvement of measuring conditions must be carried out when the aforementioned threshold values are reached.

### Note

The operator should record the overall measurement data (meter and operating data) during the entire operation in order to be able to recognize causes of potential damage at an early stage and to intervene in good time.

Remedy and/or relief of critical operating statuses can be achieved, for example, with the following measures:

- . Start-up screen (MW < 0.15 mm)
- . Filter
- . Meter protection perforated plates (Ø 3 4 mm)
- . Valves with control drive (flow change)
- Check valves (pulsation, backflow)



# 1.4.2.6 Technical guideline G13

The installation conditions for new systems according to TRG G13 and the facilitated installation conditions for RMG turbine meters are compared in the table below.

Type of up- stream per- tubation	Installation conditions according to TR G13	Installation conditions for RMG type TME400 meters	Comments	29
	$\begin{array}{l} \text{Inlet} \geq 5 \text{ DN} \\ \text{Outlet} \geq 2 \text{ DN} \end{array}$	$\begin{array}{l} \text{Inlet} \geq 2 \text{ DN} \\ \text{Outlet} \geq 2 \text{ DN} \end{array}$	The outlet pipe can also be designed as a bend.	
none	Inlet ≥ 10 DN		Pertubation upstream from this inlet pipe does not have to be factored in when the requirements for an alternating and puls- ing flow are fulfilled.	
Bend	Inlet $\ge 5 \text{ DN}$	Inlet $\ge 2 \text{ DN}$		
Bends in 2 planes	Inlet $\geq$ 5 DN <b>plus</b> 2 perforated plate straighteners or a bend straight- ener	Inlet ≥ 2 DN		
Gas pressure regulating device with an attenuator	Inlet ≥ 5 DN	Inlet ≥ 2 DN <b>plus</b> 1 perforated plate straightener		
Gas pressure regulating device without an attenuator	Inlet ≥ 5 DN <b>plus</b> 2 perforated plate straightener	Inlet ≥ 2 DN <b>plus</b> 1 perforated plate straightener		
Diffuser	Inlet ≥ 5 DN <b>plus</b> 1 perforated plate straightener	Inlet $\ge 2 \text{ DN}$		
Diffuser with swirling flow	Inlet ≥ 5 DN <b>plus</b> 2 perforated plate straightener	Inlet $\ge 2 \text{ DN}$		

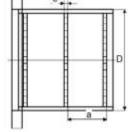
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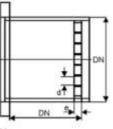


## Perforated plate straightener

The following options are available for the straighteners:

Perforated plate straightener RMG L1 - L3 according to ISO 5167-1 and DIN 1952





d = e = 0.13 ·DN

Perforate plate straightener RMG LP-35

Characteristics	ISO/DIN	L1-L3	RMG LP-35
Hole diameter d	$d \le 0.05 \ D$	0.04 D	0.13 D
Plate thickness e	$e \ge d$	e = d	0.13 D
Clearance a	$0.5 \ D \le a \le 1 \ D$	0.5 D	-
Opening ratio m	$0.2 \le m \le 0.4$	0.3	0.6
Dynamic pressure loss ∆p		5 - 15 (c² ρ / 2)	2 - 15 (c² ρ / 2)

With the RMG turbine meters, these straighteners fulfill the requirements of technical guideline G 13 and are approved with approval number D 81 / 7.211.10 for turbine meters.

#### 1.4.2.7 Standards / guidelines

All RMG turbine meters have passed upstream perturbation measurements according to OIML recommendation IR-32/89, Annex A, with slight and heavy upstream perturbation. Therefore, this meter design fulfills the installation conditions according to technical guideline G 13, section 1. The PTB testing vol. 29 and 30, testing of volume gas meters with air at atmospheric pressure and high-pressure testing rules apply as a testing requirement. The RMG turbine meter TME400 conforms to EN12261. The measuring accuracy in the range of 0.2 Q<sub>max</sub> to Q<sub>max</sub> is between  $\pm$  1.0 % to 1.5 % (see *chapter 1.4.2.9 Measuring accuracy*). The TME400 has an electronic suppression by external shut-down of the totalizer of the slow down cutoff of the turbine wheel after the flow is stopped.

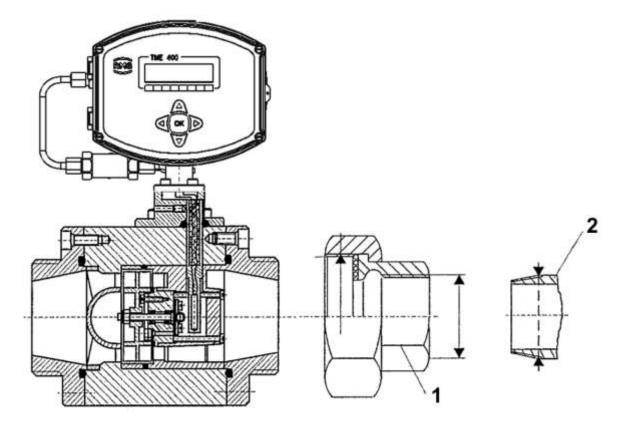
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# RMG

### 1.4.2.8 Measuring ranges

Type TME400 turbine meters have measuring ranges of at least 1:20 at atmospheric pressure (see *chapter 1.4.2.9 Measuring accuracy*). At a higher pressure, the measuring range can be expanded to 1:50. The measuring ranges are between 2.5 and 25,000 m<sup>3</sup>/h (operating conditions), depending on meter size.

The turbine meters with nominal diameter of DN25 and DN40 can be used up to a maximum of 16 bar. However, there may be restrictions for threaded connections that are subsequently used.





1 – Pipe fitting DIN2950

DN25 thread G 1 ½ ISO 228-1 DN40 thread G 2 ¼ ISO 228-1 DN25 / thread Rp 1 ISO 7-1 DN40 / thread Pp 1 ½ ISO 7-1

2 – Gas pipe

DN25 / thread R1 ISO 7-1 DN40 / thread R1 ½ ISO 7-1



According to DIN30690-1, the maximum operating pressure for non-flammable gases may not exceed 16 bar; for flammable gases, EN746-2 defines a maximum pressure of 5 bar for DN25 and 2 bar for DN40. Usually these pressure restrictions are specified on a plate on the pipe fittings.

#### 1.4.2.9 Measuring accuracy

The following error limits apply within the permissible measuring range:

				Measurement deviation in the range of		
DN	Qmin [m³/h]	Qmax [m³/h]	MR	Qmin-0,2 x Qmax [%]	0,2 x Qmax-Qmax [%]	
25	2.5	25	1:10	3	2	
40	6	70	1:12	3	1.5	
80	13	160	1:12	3	1.0	
50	6	100	1:16	3	1.5	
80	16	250	1:16	3	1.0	
	25	400	1:16	3	1.0	
100	25	400	1:16	2	1.0	
	40	650	1:16	2	1.0	
80	13	250	1:20	3	1.5	
	20	400	1:20	3	1.5	
100	20	400	1:20	3	1.5	
	32	650	1:20	3	1.5	

### Note

With a slightly smaller measuring range of 1:16, turbine meters are also available in nominal diameters DN 80 and DN 100, which have an increased accuracy with a deviation of max.  $\pm 1\%$  in the range of 0.2 x Q<sub>max</sub>-Q<sub>max</sub>.

150	32	650	1:20	2	1
	50	1000	1:20	2	1
	80	1600	1:20	2	1
200	80	1600	1:20	2	1
	125	2500	1:20	2	1
250	125	2500	1:20	2	1
	200	4000	1:20	2	1

#### 1 Introduction

33

300	200	4000	1:20	2	1
	325	6500	1:20	2	1
400	325	6500	1:20	2	1
	500	10000	1:20	2	1
500	500	10000	1:20	2	1
	800	16000	1:20	2	1
600	800	16000	1:20	2	1
	1250	25000	1:20	2	1

#### 1.4.2.10 Pressure loss

The measuring parts for determining pressure loss are 1 x DN upstream and downstream of the meter. The pressure loss is calculated according to the following formula:

$$\Delta p = Z_p \cdot \rho \cdot \frac{Q_m^2}{DN^4}$$

where:

Δр	pressure loss	[mbar]
Zp	coefficient of pressure loss	[-]
ρ	density	[kg/m³]
Qm	volume flow rate at measurement conditions	[m³/h]
DN	nominal diameter	[mm]

Device type	Zp
Turbine meter TME400	5040
Perforated plate straightener L1 according to ISO/DIN	3150
Perforated plate straightener L2 according to ISO/DIN	6300
Perforated plate straightener L3 according to ISO/DIN	9450
Perforated plate straightener LP-35 RMG standard	1260
Bend straightener RB 19 according to ISO/DIN	1260

The values for  $Z_p$  are rough averages. The exact value is calculated from the pressure loss, which is determined when testing the meter.



Example calculation for the pressure loss of a turbine meter:

#### TME400 in DN 150:

 $\begin{array}{ll} Q_m & = 650 \mbox{ m}^3/\mbox{h} \\ \rho & = 1.3 \mbox{ kg/m}^3 \mbox{ (natural gas at 600 mbar overpressure)} \\ Z_p(TME400) & = 5040 \mbox{ (see the table above)} \end{array}$ 

Calculation:

34

$$\Rightarrow \qquad \Delta p = 5040 \cdot 1.3 \cdot \frac{650^2}{150^4} \text{ mbar}$$
$$= 5.5 \text{ mbar}$$

#### 1.4.2.11 Putting the device into operation

#### Note

You receive the TME400 parameterized and calibrated according to your specifications, so that no additionally settings are generally required.

However, check whether these settings match your specifications; check the settings of the pulse width, the frequency reducer and the settings of the current output (for versions with current output).

Bring all totalizers to the meter status which you desire. (see *chapter 4.2 Programming*).



Parameters can be changed exclusively with the device open.

#### 1.4.2.12 Maintenance / lubrication

The TME 400 turbine gas meter is maintenance-free (apart from the lubrication for meters with an oil pump).

Meters in custody transfer operation must be calibrated at the prescribed intervals (according to national law). For meters in secondary operation, we recommend from a metrological point of view a check at the manufacturer every 5 to 8 years.

The TME400 is equipped with permanently lubricated bearings up to a nominal diameter of DN150 as standard. Nominal diameters of DN200 or higher are provided with an integrated lubricating device. Optionally, the TME400 can also be equipped with the "small oil pump" lubricating devices for DN25 to DN150 versions.

The type of lubricating device and the lubricant requirement depend on the nominal diameter and the pressure level:

Nominal diameter	Pressure classes	Lubricating device	Lubricant require- ment	
DN25-DN150	All pressure classes	As necessary (see below) optional small oil pump (push-button operated)	Every 3 months 6 strokes	
DN200 DN250	All pressure classes PN10 to PN16 ANSI 150	Small oil pump (push-button operated)	Every 3 months 6 strokes	
DN250	PN25 to PN100 ANSI300 toANSI600	Large oil pump	Every 3 months	
> DN300	All pressure classes	(lever operated)	2 strokes	

Also observe the notice plate on the housing.

In unfavorable conditions, e.g. with an accumulation of water and hydrocarbon condensate, as well as dust-laden gases, more frequent lubrication is recommended, even daily in extreme cases (e.g. with continuous condensate formation).

#### Note

#### **Recommended lubricating oil:**

Shell Tellus S2 MA 10 or another oil with 2 to 4°E at 25°C.



# 2 Installation

## 2.1 Electrical connections

Open the cover of the meter in order to reach the electrical connections.

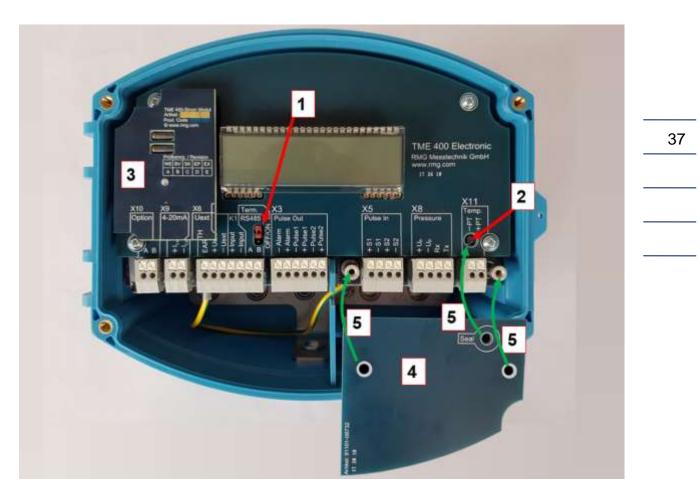


Figure 3: Unscrewing the screws to open the cover

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#### 2 Installation

# RMG



#### Figure 4: Electronics with cover of the calibration button

- 1 Jumper for RS 485 terminating resistor. Bridged: with 120  $\Omega$ ; open:  $\infty \Omega$
- 2 Calibration switch
- 3 Current module board
- 4 Cover plate for pressure and temperature sensor and calibration switch
- 5 Normal position, indicated by green arrows

#### 2 Installation

38



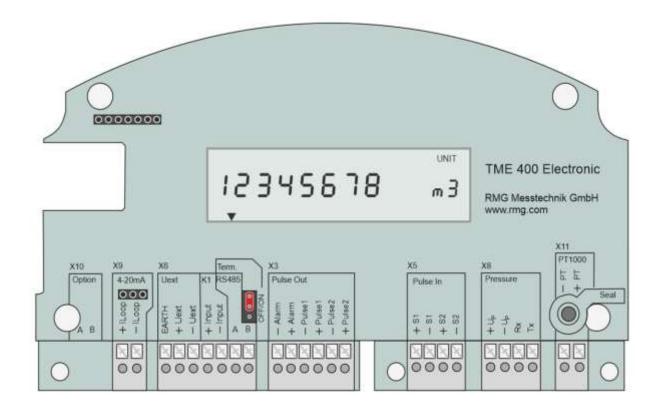


Figure 5: Connection assignment of the TME400

#### Note

Generally, no electrical connections are necessary when the turbine meter is used strictly as a flow indicator.

However, assignments are possible; the pin assignments of the TME400 are shown in in *Figure 5: Connection assignment of the TME400*. If, for example, the TME400 is to be used as a "flow sensor", the current must be connected to 4..20 mA (**terminal block X9**). The 4..20 mA current is then connected to the two terminals. For this function, the optional current module must be plugged in at the top left (see *Figure 4: Electronics with cover of the calibration button*).

The "sensor" TME400 is passive, it is fed and limits the current to the corresponding value. With this use, the current serves as an additional current supply (see *chapter 1.3.3 Power supply*). Here, care must be taken to ensure that this power supply is galvanically isolated.



If digital communication with the TME400 is required, it can be connected to the RS485. The differential signals are obtained via data lines A and B under RS485 (**terminal block X6**). Please pay attention to crossed signal lines and change the connections if appropriate. If necessary, the data interface can be conditioned using a jumper. Normally, the resistance is infinitely large ( $\infty \Omega$ ); for a point-to-point connection or if the terminal device is part of a bus system, the resistance must be set to 120  $\Omega$ .

Via "+ Uext" (external voltage supply, positive potential) and "- Uext" (external voltage supply, negative potential) the TME400 can be fed with 6-30 VDC in addition to the internal battery (in non-Ex areas). "Earth" is used for internal voltage balance. The power supply can be independent or in combination with the RS485 interface. Anyhow, this supply voltage is required for communication via the RS485 interface.

**Terminal block X6** also contains a digital input K1, which can be used to start, stop and reset the totalizer; "+Input" is the contact input for positive potential, "-Input" the contact input for negative potential.

### **A** Caution

In the Ex version, refer to the EC type approval certificate for the maximum values for the current output and the RS 485!

Via "Pulse In" (**terminal block X5**), pulses proportional to the flow rate at measurement conditions can be read from an encoder with 1 or 2 frequency outputs (main encoder and second redundant encoder if required).

Encoder (sensor) 1 is connected to the terminals via "+S1" (positive potential) and "-S1" (negative potential), encoder (sensor) 2 is connected to "+S2" and "-S2". This is especially necessary for the TME400-VMF version operated at custody-transfer applications. The sensor types can be selected in coordinates Z26/27 (see chapter 4.3.3.7 Settings). Pulse input 2 is only active if a 2-channel counting mode is selected (coordinate Z25).

Via "Pulse Out2" (**terminal block X3**) pulses and redundant pulses can be output. An alarm output can also be connected here. These six terminals combine the three digital outputs:

-Alarm: Alarm output negative potential

+Alarm: Alarm output positive potential

The alarm output works according to the closed-circuit current principle. The switching contact is closed in undisturbed condition.



-Pulse 1: HF output negative potential

+Pulse 1: HF output positive potential

At this output, the arriving pulses at pulse input 1 are synchronously with a pulse width of 1 ms.

-Pulse 2: LF output negative potential

+Pulse 2: LF output positive potential

Output pulses are output at these terminals depending on the change in the volume flow rate. The pulse output factor can be used to weight the number of output pulses in relation to the increase in volume.

For the device types TME400-VC and TME400-VCF, the dependence of the pulse output on the standard volume can also be selected (see coordinates A11 and A21). In coordinate A23 the possible pulse width can be 20ms, 125ms or 250ms.

A pressure sensor can be connected to the four connections of **terminal block X8**: "+Up" positive and "-Up" negative voltage supply for pressure sensor; "RX" or "TX" are the serial data received from the pressure sensor or sent to the pressure sensor.

The temperature sensor, a Pt1000, is connected to the terminals of terminal block X11 in two-wire connection. Pressure and temperature sensors are generally only in use with the TME400-VC and TME400-VCF versions.

The terminals of the **terminal block X10** are connections for an optional module which is not yet supported by the firmware.

Use the wire end ferrules for the connecting cable and route them in from below; a seal holds the cable. To be able to pull a cable out again, press the small white square (marked with the X) down using a small screwdriver (at the bottom in *Figure 4: Electronics with cover of the calibration button* and *Figure 5: Connection assignment of the TME400*; top of the plug strip) in order to open the locking device. Hold down the square and pull the cable out of the connector strip.

Some connection examples are given on the following pages. Anyhow, please check for further connections the data and limitations of the connected devices in the documentations of these devices.

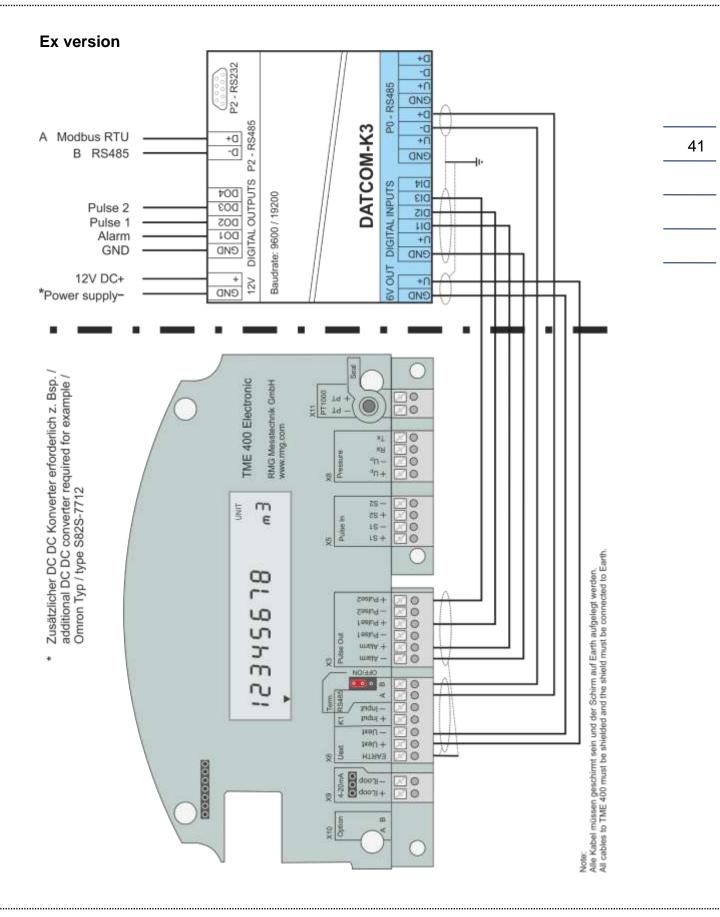
## **A** Caution

The TME400 and connected devices do not have any plugs that have a to prevent polarity reversal.

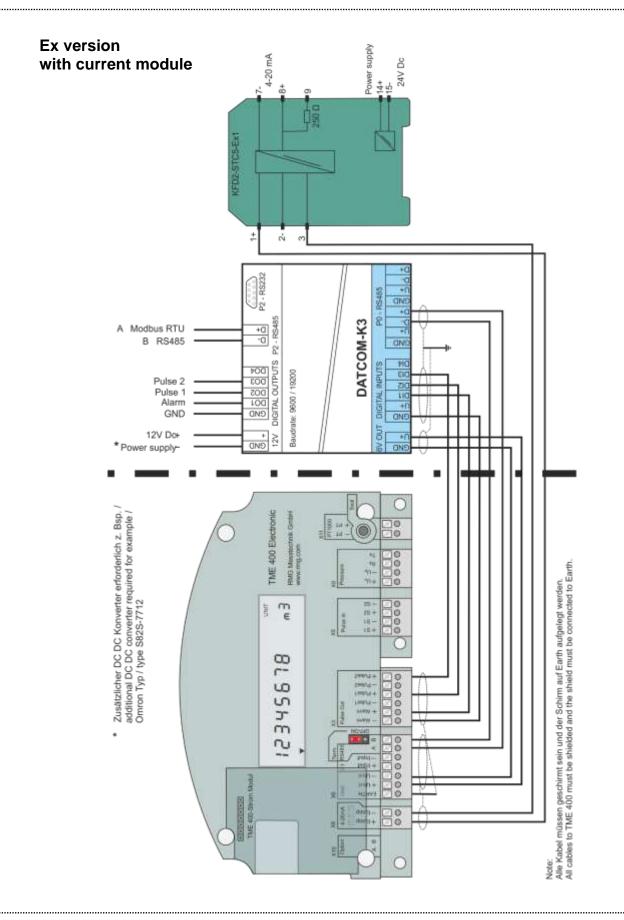
Pay careful attention to the correct connections!



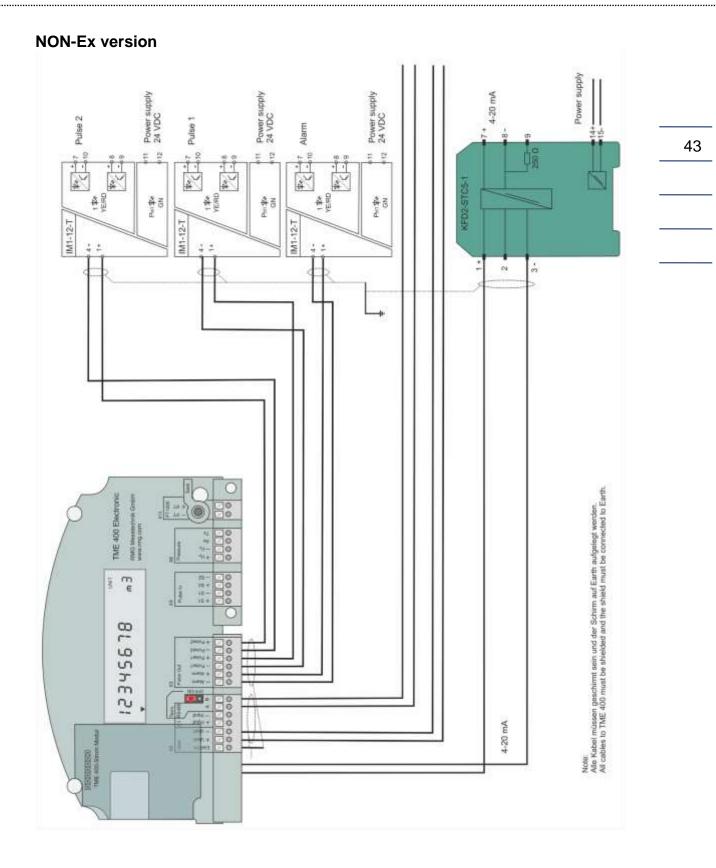
#### 2 Installation







#### 2 Installation

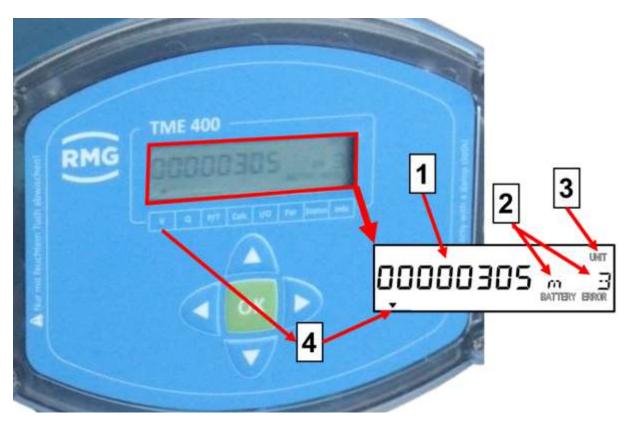




# 3 TME400

## 3.1 Display field

A single-line alphanumeric display with 12 characters enables representation of the data and measurements together with the short description or the unit.



## **Total flow volume**

Figure 6: Display field

- 1 8 characters for the value
- 3 Text: UNIT

2 Unit [m<sup>3</sup>]

4 Display arrow for volume

The LCD display and its operation are designed to save energy in order to enable battery-powered operation. The display can be impaired at temperatures below -25°C or above +60°C.



## 3.1.1 Display test

The display test is provided to ensure that all fields of the display function properly. For this purpose, please press and hold the up arrow and down arrow buttons ( and ) for more than 2 seconds. The following display appears while these buttons are held.

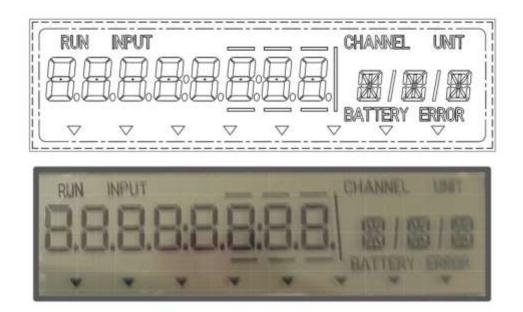


Figure 7: Display at display test

## 3.1.2 Reset

To reset the system, the voltage supply is interrupted and the TME400 is switched off for this period. For this purpose, the battery and any existing external voltage supply are disconnected. The program and operating parameters are not lost in the process and the meter statuses are saved.

## 3.1.3 Booting up

It may be necessary to re-boot the device in case of severe faults.



## Caution

It is necessary to remove the seals, particularly the seal over the calibration button in order to boot up (see *Figure 8: Position of the calibration button*).

The TME400 must only be used for custody transfer with unbroken seal. Removal or damage to seals normally entails considerable expenses!

Re-application of seals must only be carried out by an officially recognized inspection authority or calibration officials!



Figure 8: Position of the calibration button

#### Note

The current parameter settings and meter statuses are lost when re-booting! They are reset to standard values. Therefore, prior to booting up, read and store all parameters of the TME400.

#### Proceed as follows to re-boot:

- Switch off the devices
- Press the "left ◀" and "right ▶" buttons simultaneously
- Switch on the voltage again
- Then, the text "del All" appears in the display.
- Release the depressed buttons.
- Press the calibration button with a thin pencil or small screwdriver.
- Now the device is booted up and the display shows "Boot".
- Then, "done" appears in the display and the meter status of the main meter is displayed.

Then, re-transmit all device parameters to the TME400 or enter the values from the test certificated.

#### Note

The serial interface is set to 38400 Bps, 8N1, Modbus RTU after booting. These are also the default values of RMGView<sup>TME</sup> (see *chapter 4.5 RMGViewTME*).



#### 3.1.4 Battery replacement

#### Note

48

The coordinate G24 (see *chapter 4.3.3.4 Error / type plate*) indicates the remaining battery capacity. If the remaining capacity falls below 10 %, a warning is generated.

In order to replace the battery, unscrew the large screw on the right side of the electronics with a large screwdriver or a coin.



#### Figure 9: Position of the battery housing

The meter is rotated in the next figure, showing the rear area in this figure below. Now, you can pull out the battery holder with battery on a handle.

The battery can be removed vertically in relation to the battery holder by pulling slightly. When installing the new battery, ensure that the polarity is retained for the new battery.

## 🛦 Danger

The battery must only be replaced in a non-explosive atmosphere. Ensure that the electronics are supplied with adequate ventilation with fresh air.

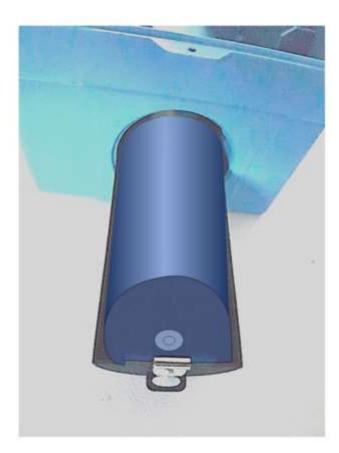


Figure 10: Battery holder

### Note

The battery can be changed during operation.

- All readings of the counter(s) and all counting parameters are retained.
- After changing the battery, the current time and date must be entered again (coordinates X01 and X02; see *chapter 4.3.3.6 Archive*). In addition, the battery change must be indicated in coordinate G25. This updates the battery change date and sets the operating hours G26 to 0 and the battery capacity G24 to 100 %.
- The current flow rate value is not stored during the change because there is no additional battery buffering.



### 🛦 Danger

According to the type examination certificate, only the following battery types may be used in potentially explosive areas: - Saft, type LS33600, 17 Ah or

- XENO, type XL 205-F, 19 Ah

## Note

You can also have the battery replaced by the RMG Service department; please contact RMG for this purpose (see page 2).

Please only use the battery types intended by RMG. They are available as spare parts.

# 4 **Operation**

## 4.1 Operation concept

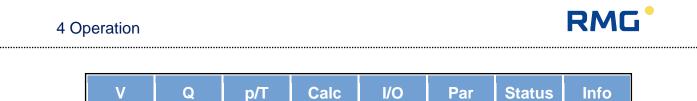


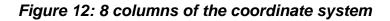
Figure 11: Front panel

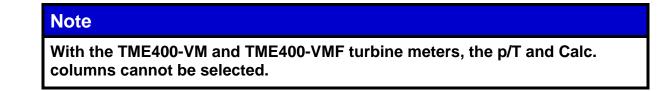
The concept of the operation is simple and easy to implement with knowledge of the coordinates.

## 4.1.1 Coordinate system

All configuration data, measurements and computed values are sorted in a table in a coordinate system which enables easy access. The coordinate system is divided into several columns, as shown on, in part, on the front panel (see *top* and *bottom*).







With the cursor buttons (arrows)

52



you can reach each value by gently pressing the desired button in this coordinate system.

Keypad	Description	Effect
	Left arrow	Switches the column of the table from right to left
	Up arrow	<b>Upward movement</b> within the column of the table: You move from the last value of the list towards the first value. This is also used to adjust numbers (counting up).
▼	Down arrow	<b>Downward movement</b> within the column of the table: You move from the first value of the list towards the last value. This is used to adjust numbers (counting down).
	Right arrow	Switches the column of the table from left to right
ОК	Function	The following functions are triggered by pressing: pressed < 2 seconds = display of the coordinate pressed > 2 seconds = switch to settings mode (see below)

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53

## 4.1.2 Display and coordinate system

The main meter is displayed in normal operating mode. The other display values can be selected with the operating buttons. After approx. 1 minute, the TME400 switches back to the main meter.

If the display is dark, the TME400 is in energy-saving mode, where the display is completely switched off. The incoming pulses are processed, and the outputs are actuated.

The display value is shown again by pressing any operating button.

Any arbitrary position in the coordinate system, which is identified by letters and numbers, can be reached with the arrow keys.

	Α	В	С	D	E	F	G	Н	Χ	Y	Ζ
01											
02						F02					
03									-		
04								Examp	le		
05											
06											
07											

Example:

RMG

F02 Current mode. The current output can be configured here.

#### 4.1.3 Parameter protection

#### Note

All custody-transfer parameters are protected by the (sealed) calibration button.

There are different access authorizations for the parameters with which unauthorized changes are suppressed. The different access rights are assigned to the coordinates by a letter. They are shown in the coordinate list. The following access levels are used:



Access level	Access right	
A	Display values, change not possible	
N	Parameter for which no password is necessary for use	
С	Code word Entry of a code word is necessary to change the parameter.	
E	Calibration button <b>Custody-transfer variant TME400-VMF:</b> Custody-transfer display values / parameters, use of the calibration button is necessary. <b>Non-custody-transfer variant TME400-VM:</b> Entry of the code word is adequate.	
	Note	
Enabling or disabling the code word or opening the cal button creates an entry in the event archive (see below)		

## 4.2 Programming

There are five buttons available on the front foil for programming of the TME400. Alternatively, you can carry out programming via the RMGView<sup>TME</sup> operating software (see *chapter 4.5 RMGViewTME*).

### 4.2.1 **Programming with the programming buttons**

Basically, you proceed as follows for the programming:

- First check the protection status of the coordinate. When parameters are not protected, you can carry out changes, as described below without additional measures.
- With parameters protected by code word, you must enter it first in coordinate Z15. Please read how to make the entry as below.
- With parameters protected for custody-transfer applications, you must press the calibration button first.

## Caution

It is necessary to remove the seals, particularly the seal over the calibration button in order to press the calibration button (see *Figure 8: Position of the calibration button*).

The TME400 must only be used for custody transfer with unbroken seal. Removal or damage to seals normally entails considerable expenses!

Re-application of seals must only be carried out by an officially recognized inspection authority or calibration officials!

The principle of the programming is shown based on the example of changing the output pulse factor:

- I. Move with the arrows (
- II. Activate the calibration button (see Figure 8: Position of the calibration button)
- III. The blinking "INPUT" text appears above the displayed value in the display view.
- IV. Press OK for more than 2 seconds
- V. The value begins to blink at a position
- VI. With the A and A arrows, you can now increase or decrease the value at this position. For the values, after the "0", you also have "-1" available in order to enter negative values, if necessary.
- VII. With the dand and arrows, you can move to a different position of the value and change it as described in the point above.
- VIII. An additional position is added when you move with the and before the displayed number. For example, only the units digit is displayed. If you move in front of it, you will also have the tens position available as an entry.
  - IX. By pressing and holding the "right" button  $\triangleright$ , the position of the decimal point is changed. After pressing and holding, the decimal point is inserted after the blinking digit.
  - X. By pressing and holding the "left" button , the entry can be canceled. If a change and/or entry is necessary, the entry must be restarted.
  - XI. When you have finished making an entry, you confirm it by briefly pressing OK
- XII. A plausibility check takes place and the result is displayed immediately.
- XIII. If this check shows an implausible entry, "rAnGE" will be shown briefly in the display and the display jumps back to the original value.
- XIV. If this check shows a plausible entry, "Good" will be shown briefly in the display and the value is adopted as a new value.
- XV. Now you can if necessary change other parameters.



- XVI. After about 1 minute without additional entries, the display returns to the display of the main meter.
- XVII. By pressing the calibration, you close the further entry of custody-transfer parameters.
- XVIII. After another minute without an entry, the change possibility is closed automatically.

#### Note

56

Some of the coordinates permit other settings as purely numerical values. However, these other entries are assigned numbers so that the adjustment can be carried out as described.

**Example:** Current mode F02 can be deactivated or activated on various settings. This is adjusted as follows:

0	Off (default)
1	No errors
2	Error 3.5 mA
3	Error 21.8 mA
4	0 - 20mA

If F02 = "0" is selected for the coordinate, the current output is switched off.

## Note

With some coordinates, a number is assigned fixed values. Instead of an adjustment with 0, 1, ..., these numerical values are shown directly. Changes are possible with the arrows **A** and **V**, then the next higher or lower value is shown and can be adopted with **OK**.

Example:

Digital output 2 pulse width (coordinate A22) can adjust the pulse width to 3 different widths. The following values can be directly as an assignment:

20 ms	
125 ms	
250 ms	

## 4.3 Equations in the TME400

The TME400 enables calculation of different values from the measured data and in the data entered in the TME400. For a better understanding, some variables and formula in this chapter are presented in advance; other equations and definitions of parameters are found in the *chapter 4.3.3. Coordinates in context.* 

Formula symbol	Units	Name
$q_m$	m³/h	Operating volume flow at measurement condition
fv	Hz	Frequency of the volume transmitter
$K_V$	l/ m <sup>3</sup>	Meter factor
$V_m$	m <sup>3</sup>	Operating volume flow rate at measurement condition
$P_V$	Nondimensional (1)	Volume pulse
Kzı	m <sup>3</sup> /l	Meter factor (only for output contacts)
K <sub>Z2</sub>	m <sup>3</sup> /l	Meter factor (only for output contacts)

### 4.3.1 Variable description

## 4.3.2 Standard formula

Variables presented from the previous chapter can be used for the basic equation for the volume flow at measurement conditions:

$$V_m = \frac{P_V}{K_V} \frac{1}{K_{Z1}}$$

(Volume flow at measurement conditions =  $\frac{Number \ of \ pulses}{Meter \ factor \ x \ Totalizer \ factor}$ )



58

#### 4.3.3 Coordinates in context

In the following, the coordinates which can be addressed with the TME400-VM and TME400-VMF turbine meters are shown. In the tables, the parameters which can be addressed with the TME400-VM are shown in light blue and the values which are **ad-ditionally** available with the version for custody-transfer applications, TME400-VMF, are shown in orange.

TME400-VM	Non-custody-transfer applica- tions
TME400-VMF	Custody-transfer applications

Coordi- nate	Name	Description
A02	Operating volume	Volumes added up at current (temperature and pressure) conditions.
A05	Uncorrected operating volume	Z26: If the characteristic correction is deactivated, A05 is not visible and cannot be adjusted. If a characteristic correction is activated, this characteristic curve correction is deactivated from 0 up to this value A05.
A06	Volume Start/Stop	Starts and stops a volume flow measurement
A07	Volume Reset	Sets the volume flow rate to 0
A10	Meter factor	With the meter factor (pulse value), the corresponding operating value flow is calculated from the signal frequency of the sensor element in the meter electronics.
		$q_m = \frac{f_V}{K_V} * 3600[\frac{m^3}{h}]$
		The meter factor must be calibrated at the factory so that a direct meter display in cubic meters.
		Note
		A change of this adjustment takes place in the responsibil- ity of the operator.
		After any change to the meter factor, calculation takes place with the new value immediately.
		The uninfluenced signal frequency of the sensor element is available at the HF output. The frequency range can be determined from the

#### 4.3.3.1 Volume / Meters

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59

		meter fa	ctor K and the minimum and maximum operating volume					
		flow of th	ne meter according to the formula:					
			$f_{V min} = \frac{q_{m min}}{3600} * K_V  f_{V max} = \frac{q_{m max}}{3600} * K_V$					
		$q_{m min}$ :minimum operating volume flow $q_{m max}$ :maximum operating volume flow						
		Example:						
		$q_{m min} = 16 \text{ m}^3/\text{h}$						
		$q_{m max} = 250 \text{ m}^3/\text{h}$						
		$K_V = 2362 \text{ pulses/m}^3$						
		$f_{V \min} = \frac{16}{3600} \frac{m^3}{s} \cdot 2362 \frac{\text{Impulse}}{m^3} = 10,5 \text{ Hz}$						
			$f_{V \max} = \frac{250}{3600} \frac{m^3}{s} \cdot 2362 \frac{\text{Impulse}}{m^3} = 164 \text{ Hz}$					
A11	Output pulse factor	The output pulse value indicates how many LF output pulses correspond to one m <sup>3</sup> (1 m <sup>3</sup> ).						
A20	Display factor	A20: Display factor for meters, including decimal places						
		0.01	(i.e. display with 2 decimal places)					
		0.1	(i.e. display with 1 decimal place)					
		1	(default) (display without decimal places)					
		10	(display without decimal places)					
		100	(display without decimal places)					
		Example: If the factor is adjusted to 0.1, the meter status is displayed with one decimal place. Note If the factor is adjusted, for instance, to 10, the display value						
		is displayed without a decimal place. You get the <u>actual</u> meter status by multiplying the display value by 10. This setting is marked with a "x 10" sticker (or it must be marked).						

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A22	Digital output 2 pulse width	20 ms 125 ms (default) 250 ms	
A12	Meter factor corrected	The meter can be adjusted by the operator, e.g. during calibration. This value does not change.	

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60

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
A02	Operating volume	302	W	Е	uint32	0	99999999	0	m <sup>3</sup>
 A05	Uncorrected operating volume	308	W	Е	uint32	0	999999999	0	m <sup>3</sup>
— A06	Volume Start/Stop	310	W	Ν	uint32	0	99999999	0	m <sup>3</sup>
A07	Volume Reset	312	W	N	uint32	0	99999999	0	m <sup>3</sup>
A10	Meter factor	500	W	Е	string12	*	*	1000.0	l/m <sup>3</sup>
A11	Output pulse factor	506	W	Е	float	0.01	100	1.0	l/m <sup>3</sup>
A20	Display factor	510	W	Е	menu16	0	4	2	
A22	Digital output 2 pulse width	512	W	N	menu16	0	2	1	ms
A12	Meter factor corrected	508	R	Α	float	-	-	1.0	l/m <sup>3</sup>

### 4.3.3.2 Flow rate

Coordi- nate	Name	Description
B02	Operating flow rate	Flow rate under current operating conditions
B03	Frequency	Unchanged output value, frequency of Sensor 1.
B05	Min. flow rate	an alarm is generated below this flow rate
B06	Max. flow rate	an alarm is generated above this flow rate
B10, B11, B12, B13; B14;	Coefficients: A-2, A-1, A0, A1, A2	<ul> <li>Z26:</li> <li>If the characteristic correction is deactivated, the additional parameters are not visible and cannot be adjusted. If a characteristic correction is activated (see Z26 below), a correction takes place with the factors in:</li> <li>B10: Factor for the characteristic correction</li> <li>B11: Factor for the characteristic correction</li> <li>B12: Factor for the characteristic correction</li> <li>B13: Factor for the characteristic correction</li> <li>B14: Factor for the characteristic correction</li> </ul>
B15	Max. operating point deviation	B15: If the deviation of the corrected from the uncorrected character- istic at an operating point (or a range) is more than the adjusted value (2% here), the correction, is set to "0" for this operating point or operating range, which means a correction takes place.
B08	Leak flow volume limit	The flow rate is disregarded below this leak flow volume limit - i.e. it is set to 0

------

B09

Maximum time > Qug + Indicates the max reaches the mea

Indicates the maximum time until the flow rate (e.g. on start-up) reaches the measuring range (Qmin) after reaching the lower measuring limit (Qug). The flow rate measurement applies as defective during this time, but no error message is generated.

Coor-	Name	Modbus	Modbus	Protec-	Data	Min.	Max.	Default	Unit	61
dinate		register	access	tion	type					
B02	Operating flow rate	320	R	А	float	-	-	*	m³/h	
B03	Frequency	322	R	А	float	-	-	*	Hz	
B05	Min. flow rate	521	W	Е	float	*	*	0.0	m³/h	
B06	Max. flow rate	523	W	E	float	*	*	1000.0	m³/h	
B10	Coefficient A-2	530	W	Е	float	*	*	0	Am2	
B11	Coefficient A-1	532	W	Е	float	*	*	0	Am1	
B12	Coefficient A0	534	W	Е	float	*	*	0	A0	
B13	Coefficient A1	536	W	Е	float	*	*	0	A1x10 <sup>-4</sup>	
B14	Coefficient A2	538	W	Е	float	*	*	0	A2x10 <sup>-8</sup>	
B15	Max. operating point de- viation	540	W	E	float	0.0	100.0	2.0	kkp	
B08	Leak flow volume limit	527	W	Е	float	*	*	*	m <sup>3</sup> /h	
B09	Maximum time > Qug +	529	W	Е	uint16	0	10000	10	S	

## 4.3.3.3 Current output

Coordi- nate	Name	Description
F01	Current	Current to be output
F02	Current mode	0 Off (default)
		1 No errors
		2 Error 3.5 mA
		3 Error 21.8 mA
		4 0 - 20mA
		If the current mode is "0", meaning "Off", in apart from parameter F02: current mode, no additional parameters of the output are visible or adjustable.
F03	Current source	0 Specification (default)
		1 Operating flow rate
		2 Frequency
		3 Calibration 4mA
		4 Calibration 20mA

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F04	Phys. minimum value	Current output phys. minimum (required for display in RMGView <sup>TME</sup> )
F05	Phys. maximum value	Current output phys. maximum (required for display in RMGView <sup>TME</sup> )
F06	Current specification	Specification value for the current output (for testing purposes)
F07	Current moderation	The current output is damped by averaging. A value of 0 corre- sponds to no damping. A value of 0.99 causes strong averaging.
F10	Calibration value 4mA	Calibration: Current value 4mA (after activation of current source)
F11	Calibration value 20mA	Calibration: Current value 20mA (after activation of current source)
F12	Module serial number	Serial number of the current module

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
F01	Current	330	R	Α	float	-	-	-	mA
F02	Current mode	657	W	Ν	menü16	0	4	0	
F03	Current source	658	W	Ν	menü16	0	7	0	
F04	Figure below	659	W	Ν	float	-	-	0.0	
F05	Picture above	661	W	Ν	float	-	-	1000.0	
F06	Current specification	663	W	Ν	float	0.0	25.0	12.0	mA
F07	Current moderation	665	W	Ν	float	0.0	0.99	0.7	I-D
F10	Calibration value 4mA	667	W	Ν	float	0.0	25.0	4.0	mA
F11	Calibration value 20mA	669	W	Ν	float	0.0	25.0	20.0	mA
F12	Module serial number	671	W	Ν	string8	-	-	0000 0000	SN

## 4.3.3.4 Error / type plate

Coordi- nate	Name	Description
G01	Current error	Identifies the current error
G02	Software version	Shows the version number of the firmware in the TME400.
G04	Serial number	Serial number of the TME400
G05	Firmware checksum	Shows the checksum of the firmware (important for TME400-VMF and TME400-VCF in custody-transfer applications)
G06	Measuring point	Possibility of numerical identification for the measuring point
G18	Meter number	Number of the turbine meter
G21	CRC metrological Param. EEprom	CRC of metrological parameters EEprom
G23	Date of Battery Exchange	Date of battery exchange

## 4 Operation

G24	Remaining Battery Capacity	Remaining capacity of the battery	
G25	Battery Change	0No (default)1Yes	
G26	Operating Hours	Operating hours	
G19	Meter size	Meter size (G )	63
G20	Date of last battery re- placement	Shows the date of the last battery replacement	

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
G01	Current error	675	R	Α	uint16	-	-	0	ERR
G02	Software version	676	R	Α	float	-	-	*	Rev
G04	Serial number	680	W	E	int32	0	99999999	01	SNo
G05	Firmware checksum	682	R	Α	int16	-	-	*	CRC
G06	Measuring point	314	W	Α	uint32	*	*	0	Rev
G18	Meter number	699	W	E	int32	*	*	9999 9999	MNo
G21	CRC metrological Param. EEprom	804	R	Α	string8	-	-	CALC	Hex
G23	Date of Battery Exchange	705	W	С	string8	-	-	010117	Bat
G24	Remaining Battery Ca- pacity	790	R	Α	uint16	-	-	100	%
G25	Battery Change	791	W	С	menü16	0	1	0	-
G26	Operating Hours	792	R	Α	uint32	-	-	0	h
G19	Meter size	701	W	E	string8	*	*	4-16000	G
G20	Date of last battery re- placement	705	W	С	int32	*	*	0101 2014	Bat

4.3.3.5 RS-485 interface

Coordi- nate	Name	Description
H01	RS-485 Baud rate	2400 Bps 9600 Bps
		19200 Bps
		38400 Bps (default)
H02	RS-485 parameter	0 8N1 (default)
		1 8E1
		2 801

64

.....



		3	7N1
		4	7E1
		5	701
H03	RS-485 protocol	0	Off
		1	Modbus RTU (default)
		2	Modbus ASCII
H04	Modbus ID	Modbu	us device address (default = 1).
H05	Modbus register offset	The of	fset is defined as 1 by RMG.

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
H01	RS-485 Baud rate	709	W	Ν	menu16	0	3	3	Bps
H02	RS-485 parameter	710	W	Ν	menu16	0	5	0	
H03	RS-485 protocol	711	W	Ν	menu16	0	2	1	
H04	Modbus ID	712	W	Ν	uint16	1	250	1	MID
H05	Modbus register offset	713	W	Ν	uint16	0	10000	1	Mof

### 4.3.3.6 Archive

Coordi- nate	Name	Description					
X01	Time	Direct entry of the current time as described above.					
X02	Date	Direct entry of the current date as described above.					
X10	Delete parameter ar- chive	0 No (default) 1 Yes					
X11	Parameter archive fill level	Display value					
X14	Delete event archive	<ul><li>0 No (default)</li><li>1 Yes</li></ul>					
X15	Event archive fill level	Display value					
X16, X17, X18, X19, X20, X21, X22, X23	Measurement archive mode	0       Off (default)         1       On         If measurement archive mode is activated, the following archives are visible and can be adjusted and deleted as necessary.         Minutes archive         X17 interval       0       15 minutes (default)         1       30 minutes         2       60 minutes					

		X18 delete	0	No (default)	
			1	Yes	
		X19 fill level	Disp	lay value	
		Day archive			
		X20 delete	0	No (default)	65
			1	Yes	
		X21 fill level	Disp	lay value	
		Month archive			
		X22 delete	0	No (default)	
			1	Yes	
		X23 fill level	Disp	lay value	
X24	Delete all Archives	All archives			
724	Delete all Archives	X24 delete	0	No (default)	
		AZ4 UEIEIE			
			1	Yes	
X12	Delete parameter ar-	0 No (default)			
	chive (E)	1 Yes			
X13					
×13	Parameter archive (E) fill level	Display value			

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
X01	Time	712	W	E	string8				Т
X02	Date	717	W	E	string8				D
X10	Delete parameter archive	722	W	Е	menu16	0	1	0	
X11	Parameter archive fill level	723	R	A	uint16	-	-	0	%
X14	Delete event archive	726	W	Е	menu16	0	1	0	
X15	Event archive fill level	727	R	A	uint16	-	-	0	%
X16	Measurement archive mode	728	W	Е	menu16	0	1	0	
X17	Minute archive interval	729	W	Е	menu16	0	2	0	
X18	Delete minute archive	730	W	Е	menu16	0	1	0	
X19	Minute archive fill level	731	R	Α	uint16	-	-	0	%
X20	Delete day archive	732	W	Е	menu16	0	1	0	
X21	Day archive fill level	733	R	Α	uint16	-	-	0	%
X22	Delete month archive	734	W	Е	menu16	0	1	0	



	X23	Month archive fill level	735	R	Α	uint16	-	-	0	%
	X24	Delete all archives	812	W	E	menu16	0	1	0	
	X12	Delete parameter archive (E)	724	W	Е	menu16	0	1	0	
66	X13	Parameter archive (E) fill level	725	R	Α	uint16	-	-	0	%

Further information about archives are in the Appendix B Structure of the archives.

Coordi- nate	Name	Description					
Z04	X:Y maximum pulse error	A differential circuit compares the metered pulse of measuring and comparison channels alternatingly. Every deviation is counted inter- nally. An alarm is generated if the adjusted limit value is exceeded. The failure counter is reset to 0 for each new measurement or after the maximum number of pulses (Z05) is reached.					
Z05	X:Y maximum pulse	see above					
Z10	Error register 1	Display value					
Z11	Error register 2	Display value					
Z12	Status register 1	Display value					
Z13	Status register 2	Display value					
710	Oberne eede word	Note The code word for the TME400 is: 1 2 3 4 This is always displayed as " **** " in the parameter archive. With entry of this code word, the protected parameters can be changed.					
Z16	Change code word	A new password can be defined here.					
Z17	Device type	0         TME400-VM (default)           1         TME400-VC           2         TME400-VMF (MID)           3         TME400-VCF (MID)					
Z24	Display active max.	<ul> <li>0 1 minute (default)</li> <li>1 5 minutes</li> <li>2 60 minute test</li> </ul>					

### 4.3.3.7 Settings

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		The time during which the display is active for tests is selected as 60 minutes. In general, however, it must be observed that higher energy consumption is associated with this time, so this time should be selected as short as possible, if possible.	
Z25	Volume metering mode	01-channel without errors (default)11-channel stop on error21-channel run on error31-channel start / stop41-channel reset52-channel stop on error62-channel run on error72-channel without X:Y error81 Channel Start/Stop Mode 2With 1-channel measurements (0, 1, 2, 3, 4), the Z04 and Z05 pulse comparison is not activated.An entry for sensor type 2 is superfluous and has no further signifi-	
		<ul> <li>cance.</li> <li>Volume metering mode 8: 1 Channel Start/Stop Mode 2</li> <li>If the external contact input 3 is closed (or opened), this additional mode 2 triggers a start (or stop) for the start/stop totalizer during this time.</li> <li>The LF output and the current output are deactivated for this period (4 mA) and no pulses are output (main totalizers stop).</li> <li>In case of an error, the pulses are counted in the error totalizers and current and pulses are output.</li> </ul>	
Z26	Characteristic correc- tion	If the TME400 is supplied with a current supply, the TME400 enables a characteristic correction via a polynomial. This correction must be activated with coordinate Z26. With this polynomial correction, the corresponding percentage deviations of the turbine meter from a reference standard are determined for fixed percentage flow rate values. From these deviations, a polynomial function which ideally reflects the curve running through these points is calculated. The coefficients of the polynomial A-2, A-1, A0, A1 and A2 are adjusted by the manufacturer in the coordinates B10 to B14 or can be entered there when the manufacturer of the turbine meter provides these values.	

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# 4 Operation

68

R	Μ	G	

		0 Off (default) 1 On					
Z27	Sensor type 1	<ul> <li>0 Reed sensor</li> <li>1 Wiegand sensor (default)</li> <li>2 External</li> </ul>					
Z28	Sensor type 2 Settings are possible, but only make sense in 2-channel operation, Settings changed here have no effect in 1-channel operation,						
	<ul> <li>0 Reed sensor</li> <li>1 Wiegand sensor (default)</li> <li>2 External</li> </ul>						
Z29	Volume unit	0 m <sup>3</sup> (Default) 1 cf					

Coor- dinate	Name	Modbus register	Modbus access	Protec- tion	Data type	Min.	Max.	Default	Unit
Z04	X:Y maximum pulse error	775	W	E	uint16	1	10000	10	Х
Z05	X:Y maximum pulse	776	W	E	uint16	1	10000	10000	Y
Z10	Error register 1	332	R	Α	int16	-	-	*	Err
Z11	Error register 2	333	R	Α	int16	-	-	*	Err
Z12	Status register 1	334	R	Α	int16	-	-	*	Sta
Z13	Status register 2	335	R	Α	int16	-	-	*	Sta
Z15	Code word release	777	W	Ν	uint16	1	9999	0	COD
Z16	Change code word	778	W	С	int16	1	9999	1234	C-V
Z17	Device type	779	W	E	menu16	0	3	0	
Z24	Display active max.	780	W	Ν	menu16	0	2	0	
Z25	Volume metering mode	781	W	E	menu16	0	7	0	
Z26	Characteristic correction	782	W	E	menu16	0	1	0	
Z27	Sensor type 1	783	W	E	menu16	0	2	1	
Z28	Sensor type 2	784	W	E	menu16	0	2	1	
Z29	Volume unit	785	W	E	menu16	0	1	0	

# Note

If the parameter is not dimensioned, the text in the "Unit" column is shown in the display of the TME400 to the right under UNIT.

# 4.4 Special settings

# 4.4.1 Configuration of the current output

The connection of external devices to the current output of the meter is to be carried out as described in chapter 2.1 *Electrical connections*.

The parameters are then set in column 'F Current output' of the coordinate matrix as follows:

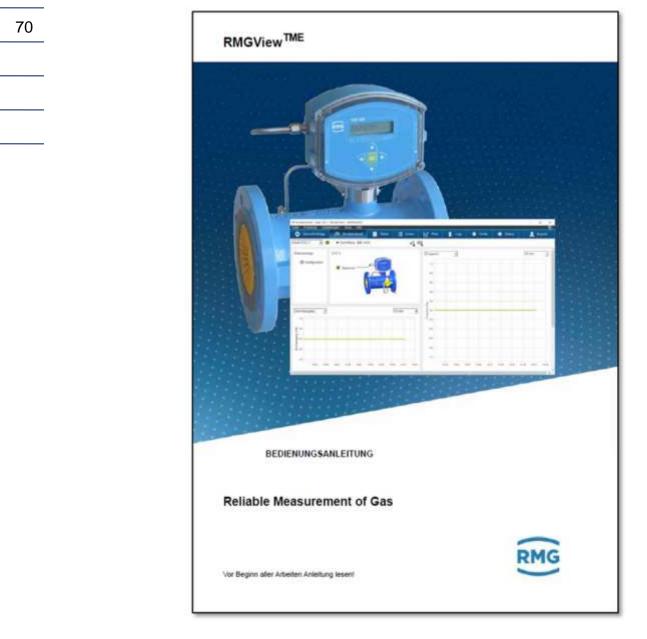
- 1. In coordinate **F-02** (current mode) select the operating mode of the current output:
  - 0: Off (default)
  - 1: 4-20mA current is always calculated from the physical value
  - 2: 4-20mA below the minimum value output of 3.5 mA
  - 3: 4-20mA above the maximum value output of 21.8 mA.
  - 4: 0-20mA
- 2. In coordinate F-03 (current source) select the value for output:
  - 0: Fixed value (default)
  - 1: Operating flow rate
  - 2: Sensor frequency
  - 3: Fixed value of 4mA for calibration
  - 4: Fixed value of 20mA for calibration
- 3. In coordinate **F-04** (physical minimum) enter the lower limit for the physical value at which 0 or 4 mA should be output.
- 4. In coordinate **F-05** (physical maximum) enter the upper limit for the physical value eintragen, at which 20 mA should be output.
- 5. In **F-06** (current specification) a fixed value can be entered for the current which is output with the entry 0 in coordinate F-02.
- 6. In **F-07** (damping) the inertia oft he output can be set with values from 0 (minimum) to 0.99 (maximum).





# 4.5 RMGView<sup>™E</sup>

The RMGView<sup>TME</sup> software also provides an additional possibility of parameter input. This software offers you additional options in combination with the TME400.



# Figure 13: RMGView<sup>™E</sup> software

For further details, please read the corresponding manual, which can be downloaded from our home page (see page 2).

# RMG

# 5 Technical data

# 5.1.1 Device types

Reed or transistor (with connected turbine meter)						
Pulse input	Reed or transistor	71				
Current output	Current loop connection (current supply via this current output possible)					
Wiegand (with connected turbine meter)						
Use	Direct installation on the TME400 turbine meter instead of the meter head					
Pulse input	Wiegand					
Current output	Current loop connection (current supply via this current output possible)					

# 5.1.2 Inputs

Volume		
Reed		
Pulse frequency	0 Hz 4 Hz	
Pulse width	≥ 20 ms	
Voltage	low: $\leq$ 0.9 V	high: $\geq$ 2.2 V
Wiegand		
Pulse frequency	0 Hz 400 Hz	z; with battery operation
Pulse width	$\geq$ 5 $\mu$ S	
Voltage	min. 1 V	max. 5 V (determined by sensor)

# 5.1.2.1 Power supply

Power supply							
Internal battery	Lithium cell 3.6 V; in the device (battery pack)						
External 6-24 V DC via X6	via U <sub>ext</sub> + battery pack (NON-Ex)						
External 6-10.5 V DC via X6	via U <sub>ext</sub> + battery pack ( <b>Ex)</b>						
External 6-24 V DC via X9	via current loop connection + battery pack						



### 5.1.2.2 Pulse In measuring inputs (sensor 1 / 2)

Note
For Ex connection values, see approval.

## 72

# 5.1.3 Outputs

Non-Ex	
U <sub>min</sub>	5 V
U <sub>max</sub> (U <sub>i</sub> )	30 V
I <sub>max</sub>	100 mA

For use of the TME400 in hazardous areas the values for the HF, LF and alarm output must be taken from the ATEX certificate.

## 5.1.4 Data interface

RS-485 data interface					
Uext	6.0 – 24 V				

For use of the TME400 in hazardous areas the values must be taken from the ATEX certificate.

## Note

When using the RS485 interface, the device must be supplied with power via  $U_{\text{ext}}. \label{eq:using}$ 

## Note

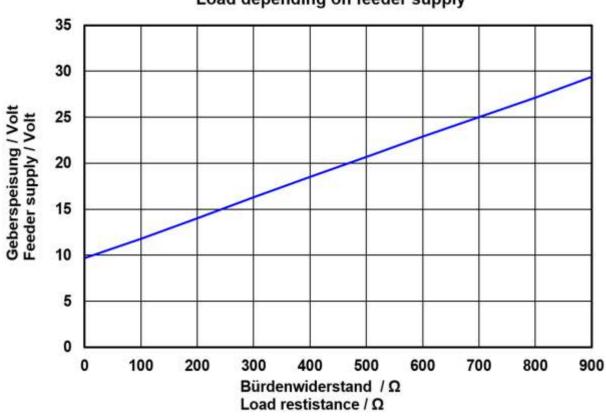
In an Ex version, the connection must only be made to a certified, intrinsic safe current circuit.

The Ex-relevant connection values are specified in the approval.

# 5.1.5 Current loop connection

<b>Current loop connection</b>					
Uext (min)	12 V				
Uext (max)	28 V				
Imin	3.5 mA		7		
Imax	23 mA	23 mA			
External resistance (max.) See: Figure 14: Load depending on feeder supply					
Current output for					
- minimum flow rate	4	mA			
- maximum flow rate	20	0 mA			
- alarm	3.	.5 mA or 21.8 mA			
Our manual acceleration of a second acceleration	the set 10/ of the set				

Current output accuracy better than 1% of the end value



Bürde in Abhänigkeit Geberspeisung Load depending on feeder supply

### Figure 14: Load depending on feeder supply

For use of the TME400 in hazardous areas the values must be taken from the ATEX certificate.



# 5.1.6 Cable

Signal cables (LF output, HF output, current loop connection, control input) must have 2 or more wires twisted in pairs and shielded (LiYCY-TP).

4-wire, twisted and shielded cables (LiYCY-TP) must be used for the data cables (RS-485).

The shielding must be grounded on both ends - on the TME400, as described in the *section 5.1.7 Cable connection*.

Cable cross-sections of 0.5 mm<sup>2</sup> are recommended. Due to the cable screw connection, the outer diameter of the cable must be between 4.5 and 6.5 mm.

▲	Ca	utio	า				
The						imited	u

The maximum cable length is limited when used in hazardous areas due to the limit values for intrinsically safe current circuits and depending on the inductivity and capacity of the cable.

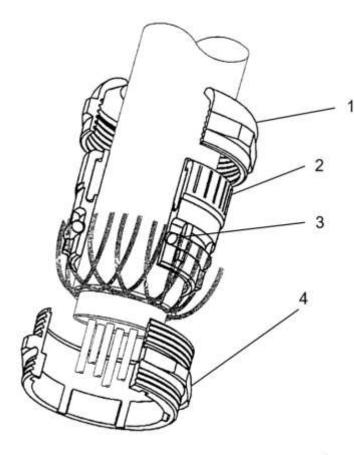
# 5.1.7 Cable connection

Connect the shield on both ends to the cable screw connections on the outside of the housing, as shown in the figure below:

- Unscrew the union nut.
- Pull the terminal insert out of the plastic.
- Slide the cable end through the union nut and the terminal insert and bend the shielding back.
- Plug the terminal insert back into the connecting piece.
- Tighten the union nut.
- Every Ex signal circuit must be routed with a dedicated cable which must be guided through the appropriate PG screw coupling.

74







- 1
- Coupling nut Terminal insert 2

- 3
- O-ring Connecting piece 4

#### 5 Technical data



## 5.1.8 Ground

### Note

To avoid measuring errors due to electromagnetic interference, the meter housing <u>must</u> be grounded with the ground connection on the right section of the housing (see *Figure 16: Grounding the meter*).

Minimum cable cross-section:

- length of up to 10 m: 6 mm<sup>2</sup>
- length of 10 m or higher:10 mm<sup>2</sup>



#### Figure 16: Grounding the meter

In the process, a conductive connection between the TME400 and the pipeline must be provided as shown in the figure below.



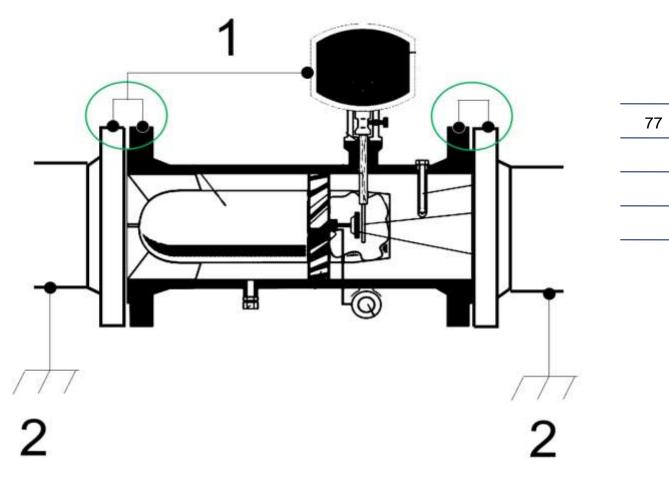


Figure 17: Grounding with the connecting pipes

- Equipotential bonding conductor (PE) min. 6 mm<sup>2</sup> Measuring system potential 1
- 2



# 5.2 Overview of materials in use

Name	Material
Housing	Cast iron, cast steel, stainless steel, aluminum or welded steel
Flow straightener	Delrin, aluminum or steel
Turbine wheel	Delrin or aluminum
Measuring unit	Aluminum
Ball bearings	Stainless steel
Shafts	Stainless steel
Gear wheels	Stainless steel or plastic
Magnetic coupling	Stainless steel
Meter head	Plastic
Meter printed circuit board	Aluminum, zinc die-casting or brass

78

# RMG

# 6 Error messages

Error messages are shown in the display as an error number and "unit" "Err".



## Figure 18: Error message in the display

The message types are:

E = ErrorW = Warning H = Hint

There are the following error messages:

Message type	Error no.	Brief description	Comment
E	1	EEprom version error	Contact RMG service.
Е	2	EEprom error	Contact RMG service.
E	8	Flow rate min/max error	Check the alarm setting for the flow rate.

# 6 Error messages

80



E	9		X:Y pulse comparison error	Check the alarm setting for the pulse comparison.
Е	10		Max. output pulse error	Check the alarm setting for the max. output pulse.
E	11		Current output error	Check your current connections. Contact RMG service in case of uncertainty.
Е	12		Error CRC Calibration Parameter	Contact RMG service.
W	101	M	/arning Battery Capacity low	Please change the battery
W	101	M	Arning Battery Capacity low	Please change the battery
W	101 201		Varning Battery Capacity low	Please change the battery You have a new firmware version
		N		

# RMG

# Appendix

# A Modbus

The TME400 has a passive RS-485 interface, which means the interface must be supplied with power externally.

### Parameterizing the Modbus

#### **Modbus activation**

H03 RS-485 protocol

0	Off
1	Modbus RTU (default)
2	Modbus ASCII

The Modbus - ID is adjusted via the coordinate H04 (default is 1)

The **Modbus - Register - Offset** (MRO) is entered via coordinate H05 (default is 1). The MRO applies for read and write operations.

#### **Baud rate**

H01 Baud rate RS-485 interface

0	2400 Bps	
1	9600 Bps	
2	19200 Bps	
3	38400 Bps (default)	

#### Interface parameters

The interface parameters can be adjusted in coordinate H02. H02 RS-485 interface parameters

0	8N1 (default)
1	8E1
2	801
3	7N1
4	7E1
5	701



#### The TME400 recognizes the following Modbus commands:

- (03 Hex) Read Holding Registers
- (06 Hex) Preset Single Register
- (10 Hex) Preset Multiple Regs
- (08 Hex) Subfunction 00 Hex: Return Query data

#### **TME400 Exception Codes**

- 01 Illegal Function
- 02 Illegal Data Address (register not available)
- 03 Illegal Data Value (register not writable or incorrect value)

#### Example (Modbus query/response):

Query:	Send character	
Start Char		
Slave Address	01	
Function	03	
Starting Address Hi	07	
Starting Address Lo	CF	2000-1
No. of Points Hi	00	
No. of Points Lo	02	
LRC	24	
carriage return	cr	
line feed	lf	
Response:	Receive character	
Start Char	:	
Slave Address	01	
Function	03	
Function Byte Count	03 04	
		see below
Byte Count	04	see below see below
Byte Count Data Hi (Reg 2000)	04 3F	
Byte Count Data Hi (Reg 2000) Data Lo (Reg 2000)	04 3F 80	see below
Byte Count Data Hi (Reg 2000) Data Lo (Reg 2000) Data Hi (Reg 2001)	04 3F 80 00	see below see below

lf

line feed

## Example (Modbus number formats)

Data type	Reg- ister	Value	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7	Byte 8	Byte 9	Byte 10
float	2	1.0	0x3f	0x80	0x00	0x00						
Text	5	"90111200"	0x39	0x30	0x31	0x31	0x31	0x32	0x30	0x30	0x00	0x00
int	1	1357	0x05	0x4d								
long	2	698614	0x00	0x0a	0xa8	0xf6						

Refer to the Modbus specifications for further information.

### Characteristics of the TME400 Modbus

- Data types (float, text ...) can only be read or written completely

menu16	:	1 Register
int16	:	1 Register
uint16	:	1 Register
int32	:	2 Register
uint32	:	2 Register
float	:	2 Register
string8	:	4 Register
string12	:	6 Register

- A maximum of 125 registers can be read or written (in one command)..
- Text fields must have at least one terminating zero (0x00).
- Writing of certain parameters causes internal initialization of the hardware and/or:
  - Deletion of intermediate results (pulse output, meter calculation, etc.).
  - Therefore, the parameters should only be overwritten as necessary (e.g. meter factor)
  - Meter statuses are delivered as a uint32 value (without decimal)

# Modbus - Register (Version:0.001; Matrix: 001; June 2018)

M		Reg. number	Data type	MB acces	Coordina ss	ate Name	Access	Unit	Des	cription
30	)2	2	uint32	RW	A02	Volume Mea- surement	E	&VolumeUn	117	ume at measure- nt conditions
30	)6	2	uint32	RW	A04	Volume Mea- surement Error	E	&VolumeUn	nit -	ume at meas. ditions error
— 30	)8	2	uint32	RW	A05	Volume Mea- surement un- cor.	E	&VolumeUn	nit mer	ume at measure- nt conditions un- ected
31	0	2	uint32	RW	A06	Volume Start/Stop	N	&VolumeUn	nit Volu	ume Start/Stop
- 31	2	2	uint32	RW	A07	Volume Reset	Ν	&VolumeUn	nit Volu	ume Reset
31	4	2	uint32	RW	G06	Metering Point	E		Nan	ne of met. point
Mi		Reg. number	Data type	MB acces	Coordina ss	te Name	Acces	s Unit	Descr	iption
32	20	2	float	R	B02	Flow Rate Mea- surement	А	&FlowUni	t Flow r ment	ate measure-
32	22	2	float	R	B03	Frequency	А	Hz	Frequ	ency
33	30	2	float	R	F01	Current	А	mA	Curren	nt to be output
33	32	1	uint16	6 R	Z10	Error Register 1	А	Hex	Error I	register 1
33	33	1	uint16	B R	Z11	Error Register 2	А	Hex	Error I	register 2
33	34	1	uint16	6 R	Z12	Status Register	1 A	Hex	Status	register 1
33	35	1	uint16	6 R	Z13	Status Register 2	2 A	Hex	Status	s register 2
M		Reg. number	Data type	MB acce	Coordina ss	ite Name	Access	Unit		Description
50	00	6	string1	2 RW	A10	Meter Factor	E	&CounterFa	ctorUnit	Meter factor
50	)6	2	float	RW	A11	Output Pulse Factor	E	&CounterFa	ctorUnit	Output pulse factor
50	8	2	float	R	A12	Meter Factor corrected	A	&CounterFa	ctorUnit	Meter factor corrected
51	0	1	menu	I6 RW	A20	<b>Display Factor</b>	E			Display factor
51	1	1	menu	16 RW	A21	Digital Output 2 Mode	E			Digital output 2 mode
51	2	1	menu	I6 RW	A22	Digital Output 2 Pulse Width	Ν	ms		Digital output 2 pulse width
M		Reg.		MB access	Coordinate	Name	Acces	s Unit	Descr	iption
52	21 2	2	float	RW	B05	Flow Rate min.	Е	&FlowUni	t Flow r	ate minimum
52	23 2	2	float	RW	B06	Flow Rate max.	Е	&FlowUni	t Flow r	ate maximum
MI		Reg. number	Data type	MB access	Coordinate	Name	Access	Unit	Descrip	tion
52	27 2	2	float	RW	B08	QmUg	Е	&FlowUnit		

# RMG

#### APPENDIX

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529	1	uint16	RW	B09	QmMinTime	Е		6		
530	2	float	RW		Coefficient A-2	E		Am2	Error curve linearization	
550	2	noat	17.0.0	ы	Coefficient A-2	-		-\IIIZ	coefficent A-2 Error curve linearization	
532	2	float	RW	B11	Coefficient A-1	Е	1	Am1	coefficent A-1	
534	2	float	RW	B12	Coefficient A0	Е		40	Error curve linearization coefficent A0	
536	2	float	RW	B13	Coefficient A1	Е		41	Error curve linearization coefficent A1	85
538	2	float	RW	B14	Coefficient A2	Е		42	Error curve linearization	
540	2	float	RW		KKMaxProz	E			coefficent A2	
						L				
MB reg	Reg. num- ber	Data type	MB ac- cess	Coordinate	Name		Acces	s Unit	Description	
657	1	menu16		F02	Current Mode		N		Mode current output	
658	1	menu16	RW	F03	Current Source		N		Source current output	
659	2	float	RW	F04	Physical minimum value		N		Current output phys. mini- mum value	
661	2	float	RW	F05	Physical maximum value	۱	N		Current output phys. maxi- mum value	
663	2	float	RW	F06	Current default		N	mA	Current output default	
665	2	float	RW	F07	Current Damping		Ν	I-D	Damping current output	
667	2	float	RW	F10	Calibration Value 4m	۱A	Ν	mA	Calibration: Actual value 4mA	
669	2	float	RW	F11	Calibration Value 20mA		N	mA	Calibration: Actual value 20mA	
671	4	string8	RW	F12	Module Serial Nun ber	<b>n-</b>	N	SN	Current output module se- rial no.	
675	1	uint16	R	G01	Current Error		A	ERR	Current activated error codes	
676	2	float	R	G02	Software Version		А	Rev	Software version	
MB reg	Reg. num- ber	Data type	MB ac- cess	Coordinate	Name		Acces	s Unit	Description	
680	2	int32	RW	G04	Serial number		E	SNr	Serial number	
682	1	uint16	R	G05	Firmware Checksum	۱	А	CRC	Firmware checksum	
683	2	float	R	G10	Pressure Base		А	bar	Pressure at base condition	
685	2	float	R	G11	Pressure Range Mir	۱.	А	bar	Pressure range minimum	
687	2	float	R	G12	Pressure Range Ma	х	A	bar	Pressure range maximum	
689	6	string12	R	G13	Pressure Sensor Serial Number		A		Serial number pressure sensor	
695	2	float	R	G14	Temperature Base	Э	А	TN	Temperature at base condition	
697	2	int32	RW	G17	Temp. Sensor Se- rial Number		E	TNr	Serial number tempera- ture sensor	

# APPENDIX



	699	2	int32	RW	G18	Serial Number Gas Meter	E	ZNr	Serial number gas meter	
	701	4	string8	RW	G19	Meter size	E	G	Meter size	
	705	3	string8	RW	G20	Date of Battery Exchange	С	Bat	Date of battery exchange	
86	790	1	uint16	R	G24	Remaining Battery Capacity	А	%	Remaining Battery Ca- pacity	
	791	1	menu16	RW	G25	Battery Change	С	-	Battery Change	
	792	2	uint16	R	G26	Operating Hours	А	h	Operating Hours	
	MB reg	Reg. number	Data type	MB access	Coordinate	Name	Access	Unit	Description	
	709	1	menu16	RW	H01	RS485 Baudrate	Ν	Bps	RS485 interface baudrate	
	710	1	menu16	RW	H02	RS485 Parameter	Ν		RS485 interface parameter	
	711	1	menu16	RW	H03	RS485 Protocol	Ν		RS485 selection of protocol	
	712	1	uint16	RW	H04	Modbus ID	Ν	MID	Modbus ID	
	713	1	uint16	RW	H05	Modbus Register Offset	Ν	Mof	Modbus register offset	
	714	3	string8	RW	X01	Time	E	Т	Time	
	717	3	string8	RW	X02	Date	E	D	Date	
	MB reg	Reg. number	Data type	MB access	Coordinate	Name	Acces	ss Un	it Description	
	700	4				Delete Parameter Ar-	_		Delete parameter ar-	
	722	1	menu16	RW	X10	chive	Е		chive	
	722	1	uint16	R	X10 X11		E	%		
						chive Fill level Para. Archive Delete Parameter Ar- chive(E)	E A E	%	chive Fill level parameter ar- chive Delete parameter ar- chive (E)	
	723	1	uint16 menu16 uint16	R RW R	X11 X12 X13	chive Fill level Para. Archive Delete Parameter Ar-	E A E	%	chive Fill level parameter ar- chive Delete parameter ar-	
	723 724 725 726	1 1 1 1	uint16 menu16 uint16 menu16	R RW R RW	X11 X12 X13 X14	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive	E A E A E	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> </ul>	
	723 724 725 726 727	1 1 1 1 1 1	uint16 menu16 uint16 menu16 uint16	R RW R RW R	X11 X12 X13 X14 X15	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive	E A E A E E E A	Ļ	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Fill level event archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> </ul>	1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 uint16 menu16	R RW R RW R RW	X11 X12 X13 X14 X15 X16	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives	E A E A E A E A E A E	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> </ul>	1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 uint16 menu16 menu16	R RW R RW R RW RW	X11 X12 X13 X14 X15 X16 X17	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive	E A E A A E A E A E A E C A E	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> </ul>	1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 menu16 menu16 menu16	R RW R RW R RW RW RW RW	X11 X12 X13 X14 X15 X16 X17 X18	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Delete Minute Archive	E A E A E E A E E E E E E E	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> <li>731</li> </ul>	1 1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 menu16 menu16 menu16 uint16	R RW R RW R RW RW RW R	X11 X12 X13 X14 X15 X16 X17 X18 X19	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Fill level Minute Archive	E A E A E A E A E E E E A	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> <li>Fill level minute archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> <li>731</li> <li>732</li> </ul>	1 1 1 1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 uint16 uint16 menu16 menu16 uint16 menu16	R RW RW RW RW RW RW RW RW	X11 X12 X13 X14 X15 X16 X17 X18 X19 X20	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Fill level Minute Archive Delete Day Archive	E A E A E A E A E E C E A E A E	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> <li>Fill level minute archive</li> <li>Delete day archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> <li>731</li> <li>732</li> <li>733</li> </ul>	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 menu16 menu16 uint16 uint16 uint16	R RW RW RW RW RW RW RW RW RW RW R	X11 X12 X13 X14 X14 X15 X16 X17 X18 X18 X19 X20 X21	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Fill level Minute Archive Fill level Minute Archive Fill level Day Archive	E A E A E A E A E E C A E A A A	%	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> <li>Fill level minute archive</li> <li>Fill level ay archive</li> <li>Fill level day archive</li> </ul>	
	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> <li>731</li> <li>732</li> <li>733</li> <li>734</li> </ul>	1 1 1 1 1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 menu16 menu16 uint16 uint16 uint16 menu16	R W R W R W R W R W R R R R R R R R R R	X11 X12 X13 X14 X15 X16 X17 X18 X19 X20 X21 X22	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Fill level Minute Archive Fill level Minute Archive Fill level Day Archive Fill level Day Archive	E A A A A A A A A A A A A A A A A A A A	% % %	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> <li>Fill level minute archive</li> <li>Delete day archive</li> <li>Fill level day archive</li> <li>Delete month archive</li> </ul>	
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	<ul> <li>723</li> <li>724</li> <li>725</li> <li>726</li> <li>727</li> <li>728</li> <li>729</li> <li>730</li> <li>731</li> <li>732</li> <li>733</li> <li>734</li> </ul>	1 1 1 1 1 1 1 1 1 1 1 1 1 1	uint16 menu16 uint16 menu16 menu16 menu16 uint16 uint16 uint16 menu16	R W R W R W R W R W R R R R R R R R R R	X11 X12 X13 X14 X15 X16 X17 X18 X19 X20 X21 X22	chive Fill level Para. Archive Delete Parameter Ar- chive(E) Fill level Para. Achive (E) Delete Event Archive Fill level Event Archive Mode archives Interval Minute Archive Fill level Minute Archive Fill level Minute Archive Fill level Day Archive Fill level Day Archive	E A A A A A A A A A A A A A A A A A A A	% % %	<ul> <li>chive</li> <li>Fill level parameter archive</li> <li>Delete parameter archive (E)</li> <li>Fill level parameter archive (E)</li> <li>Delete event archive</li> <li>Delete event archive</li> <li>Fill level event archive</li> <li>Mode Archives</li> <li>Interval minute archive</li> <li>Delete minute archive</li> <li>Fill level minute archive</li> <li>Delete day archive</li> <li>Fill level day archive</li> <li>Delete month archive</li> </ul>	

# RMG

### APPENDIX

775	1	uint16	RW	Z04	X:Y maximum Pulse Errors	E	х	Pulse compare X:Y max- imum pulse errors	
776	1	uint16	RW	Z05	X:Y maximum Pulses	E	Y	Pulse compare X:Y max- imum pulses	
777	1	uint16	RW	Z15	Code Word Input	Ν	COD	Code word input	
778	1	uint16	RW	Z16	Code Word Change	С	C-V	Code word change	
779	1	menu16	RW	Z17	Device Type	E		Device type	87
780	1	menu16	RW	Z24	Display on max.	N		Maximum time display on	
781	1	menu16	RW	Z25	Volume Count Mode	E		Selection mode of vol- ume counter	
782	1	menu16	RW	Z26	Curve Linearization	E		Selection curve linearization	
783	1	menu16	RW	Z27	Sensor Type 1	E		Selection turbine sensor channel 1	
784	1	menu16	RW	Z28	Sensor Type 2	E		Selection turbine sensor channel 2	
785	1	menu16	RW	Z29	Unit Volume	E		Selection volume unit	
819	1	uint16	R	Z42	Warning Register 1	А	Hex	Warning register 1	
820	1	uint16	R	Z43	Warning Register 2	А	Hex	Warning register 2	
821	1	uint16	R	Z44	Hint Register 1	А	Hex	Hint register 1	
822	1	uint16	R	Z45	Hint Register 2	А	Hex	Hint register 2	

The Modbus access has the meaning:

R = no protection RW = calibration button



## APPENDIX

## Error, warning, hint and status registers

MB reg	Reg. number	Data type	MB access	Bit	Description	Event number
				0		-
				1	Error: Power-Fail	1
				2	Error: EEprom	2
				3	Error: Pt1000-Hardware	3
				4	Error: Temperature min/max	4
				5	Error: Pressure Sensor-Hardware	5
332	1	uint16	R	6	Error: Pressure min/max	6
552	1	unitro	IX	7	Error: Calculation Gas Equations	7
				8	Error: Flow min/max	8
				9	Error: Pulse Comparison X:Y	9
				10	Error: max. Output Pulses	10
				11	Error: Current Output	11
				12	Error: CRC Calibration Parameter	12
				13 15	-	-
333	1	uint16	R		Not assigned	-
		uint16		0	-	-
				1	Status: Code Word enabled	
				2	Status: Calibration switch open	
				3	Status: External Power Supply RS485 on	
334	1		R	4	Status: Current Loop on	
554	1		IX	5	Status: Pulse Input 1 closed	
				6	Status: Pulse Input 2 closed	
				7	Status: Digital Input 1 closed	
				8	Status: Battery Capacity < 10%	
				9 15	-	-
335	1	uint16	R		Not assigned	-
				0	-	-
819	1	uint16	R	1	Warning: Battery Capacity < 10%	101
				2 15	-	-
820	1	uint16	R		Not assigned	-
			R	0 1	-	-
821	1	uint16		2	Hint: Calibration Switch open	202
521	'			3	Hint: Code Word enabled	203
				4 15		-
822	1	uint16	R		Not assigned	-

88

# RMG

# **B** Structure of the archives

In this appendix you will find more information about the archives:

- Archive size
- Archive types
  - Parameter archives
  - o Event archives
  - o Measured values archives
- Calculation of the storage size
- Archive header
- Reading the archive data via Modbus

# B1 Archive size

The TME400 has an archive storage divided into the following archive types with the given archive sizes:

Event archive	200 Entries
Parameter archive (custody transfer)	300 Entries
Parameter archive (non-custody transfer)	300 Entries
Month archive	25 Entries
Day archive	100 Entries
Periodic archive	9000 Entries

# B2 Archive types

Below is a list of further data on the parameter, event and measured value archives.



#### **B2.1** Parameter archives

The parameter archive contains the history of all parameter changes. The time of the change and the old and the new parameter values are stored in the archive.

The parameter archives are divided into one archive each for custody transfer and non-custody transfer parameters.

#### Internal structure of an entry:

Content	Data type	Length in Bytes
Position number	UINT16	2
Unix time (device time)	UINT32	4
Coordinate	UINT16	2
Old parameter value	CHAR	12
New parameter value	CHAR	12
CRC16 (Modbus)	UINT16	2
		Total length: 34

Coordinate:

- High byte: column ("A"-"Z" as ASCII)
- Low byte: line

A value in the coordinate field 4103h corresponds to coordinate A 03.

#### **B2.2 Event archives**

The event archive stores error messages, warnings and notes that occurred or disappeared during operation of the TME400.

#### Internal structure of an entry:

Content	Data type	Length in Bytes
Position number	UINT16	2
Unix time (device time)	UINT32	4
Event type	UINT16	2
Event number	UINT16	2
CRC16 (Modbus)	UINT16	2
		Total length: 12

90



Event type:

- High byte: type ('E' = error, 'W' = warning, 'H'= note)
- Low byte: 0 = Event passes, 1 = Event is coming

#### **B2.3 Measured values archives**

In the measured value archives, meter readings and average values of important measured variables are periodically stored.

There are three types of measured value archives implemented:

- Periodic archive (adjustable: 15, 30 or 60 minutes)
- Daily archive
- Monthly archive

#### Internal structure of an entry:

Content	Data type	Length in Bytes
Position number	UINT16	2
Unix time (device time)	UINT32	4
Standard volume	UINT32	4
Operating volume	UINT32	4
Standard volume Error	UINT32	4
Operating volume Error	UINT32	4
Exponent (to base 10)	INT16	2
Mean pressure	FLOAT	4
Mean temperature	FLOAT	4
Mean compressibility	FLOAT	4
Status	UINT16	2
CRC16 (Modbus)	UINT16	2
		Total length: 40

91



# **B3** Calculation of the storage size

The total available storage for archives is 506880 bytes.

Archive type	Bytes / entry	Amount entries	Sum in bytes
Parameter archive (custody transfer)	34	300	10200
Parameter archive (non-custody transfer)	34	300	10200
Event archive	12	200	2400
Periodic archive	40	9000	360000
Daily archive	40	100	4000
Monthly archive	40	25	1000
Sum			387800

# **B4** Archive header

Each archive type contains an administration header that gives information about how to access the archive.

#### The header is arranged as follows:

Content	Data type	Length in Bytes
Position number of the next archive (largest value = 9999, then again = 0)	UINT16	2
Index oldest entry	UINT16	2
Index newest entry	UINT16	2
CRC16 (Modbus)	UINT16	2
		Total length: 8

There are four headers for each archive type, which are organized in memory as ring buffers. This is to ensure that the information is stored safely in case of cell defects in the EEprom. Each time a new archive entry is written, the corresponding archive header is updated and stored as the next entry in the ring buffer:

## Empty header ring buffer at the beginning after writing a new entry:

Storage index	
0	Archive header (Position number 1) -> Actual header
1	empty
2	empty
3	empty

## Ring buffer after the writing of four entries:

Storage index	
0	Archive header (Position number 1)
1	Archive header (Position number 2)
2	Archive header (Position number 3)
3	Archive header (Position number 4) -> Actual header

# Ring buffer after the writing of six entries:

Index	
0	Archive header (Position number 5)
1	Archive header (Position number 6) -> Actual header
2	Archive header (Position number 3)
3	Archive header (Position number 4)

### Content of an empty header:

Content	Data type	Value
Position number of the next archive	UINT16	0
Index of the oldest entry	UINT16	FFFFh
Index of the newest entry	UINT16	FFFFh
CRC16	UINT16	xxxxh

## Content of the header after the writing of the first archive entry:

Inhalt	Data type	Value
Position number of the next archive	UINT16	1
Index of the oldest entry	UINT16	0
Index of the newest entry	UINT16	0
CRC16	UINT16	xxxxh

#### Content of the header after the writing of the second archive entry:

Content	Data type	Value
Position number of the next archive	UINT16	2
Index of the oldest entry	UINT16	0
Index of the newest entry	UINT16	1
CRC16	UINT16	xxxxh

Content header after the writing of the 300<sup>th</sup> archive entry (archive full):

Content	Data type	Value
Position number of the next archive	UINT16	300
Index of the oldest entry	UINT16	0
Index of the newest entry	UINT16	299
CRC16	UINT16	xxxxh

# Content header after the writing of the 301<sup>st</sup> archive entry (archive full, oldest entry overwritten in the ring buffer):

Content	Data type	Value
Position number of the next archive	UINT16	301
Index of the oldest entry	UINT16	1
Index of the newest entry	UINT16	0
CRC16	UINT16	xxxxh

Procedure for determining the indexes to be read in the archive:

- Reading all four archive headers of an archive type
- Recognizing the current header
- Determine the range to be read: If "Index oldest entry" = FFFFh and "Index newest entry" = FFFFh, then the corresponding archive is empty

If "Index oldest entry" = 0 and "Index newest entry" = 0, then the archive contains an entry

- If "Index oldest entry" < "Index newest entry", then the Number of entries = "Index newest entry" - "Index oldest entry" + 1
- If "Index oldest entry" > "Index newest entry", then the No. of ent. = max. archive ent. - "Index older ent." + "Index newest ent." + 1 (Archive is always full: Number of entries = Maximum archive entries, Calculation for the purpose of completeness only)

# **B5** Reading the archive data via Modbus

RMG

Archive entries are accessible via Modbus. The command 14h "Read General Reference" is used for this. This command can be used to index the storage ranges of the archives and the corresponding management headers (see document: "Modicon Modbus Protocol; Reference Guide (PI-MBUS-300 Rev. J)")

The TME400 only supports the processing of a sub-request within one request.

Byte	Meaning
1	Device address
2	Function (14h)
3	Number of bytes (07h)
4	Reference type (00h)
5	File number (Hi)
6	File number (Lo)
7	Start index (Hi)
8	Start index (Lo)
9	Number of registers to be read (Hi)
10	Number of registers to be read (Lo)
11	CRC (Lo)
12	CRC (Hi)

The structure of the request string is as follows:

The specified reference type in the request string is not checked in the TME400.

File number	Archive type
1	Management header custody transfer parameter archive
2	Custody transfer parameter archive
3	Management header parameter archive
4	Parameter archive
5	Management header event archive
6	Event archive
7	Management header minutes archive
8	Minutes archive
9	Management header daily archive
10	Daily archive
11	Management header monthly archive
12	Monthly archive

## The following file number selects the archive or archive header to be read:

95



With the file address the index of the archive to be read is selected.

The number of registers of the bytes which are read from an archive entry (number of bytes = number of registers x 2). The maximum number of registers to be read is limited to 125 per request.

The following example shows the data to be read in a request:

- File number: 6 (Event archive, size: 12 Byte per entry)
- Start index: 7 (Read from index 7)
- Number of registers: 13

Archive index	Modbus register	Internal storage address of the TME400
7	1 (Hi)	0 (+ Offset)
	1 (Lo)	1 (+ Offset)
	2 (Hi)	2 (+ Offset)
	2 (Lo)	3 (+ Offset)
	6 (Hi)	10 (+ Offset)
	6 (Lo)	11 (+ Offset)
8	7 (Hi)	12 (+ Offset)
	7 (Lo)	13 (+ Offset)
	8 (Hi)	14 (+ Offset)
	8 (Lo)	15 (+ Offset)
	12 (Hi)	22 (+ Offset)
	12 (Lo)	23 (+ Offset)
9	13 (Hi)	24 (+ Offset)
	13 (Lo)	24 (+ Offset)

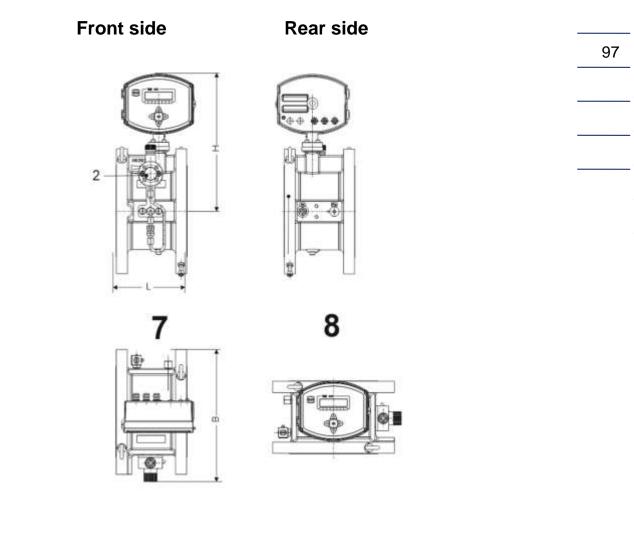
The example shows the reading of two complete event archive entries (index 7 and 8) and a part archive (2 bytes from index 9). In practice, it makes sense to request only complete archives. The above case is used exclusively to illustrate the mechanism.

96

# **C** Dimensions

TME400-VM

RMG



- 1 -
- 2 Oil pump
- 3
- 4 ·

- 5 -
- 6
- 7 Top view
- 8 Top view for flow direction from bottom top up to DN200



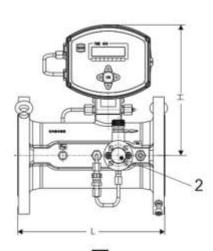
Size		Max. Flow rate	Din	Weight			
		Qmax					
mm	Inch	m3/h	Length L	Width B	Hight H		
25	1	25	185	135	225	2	
40	1 1/2	70	140	255	225	5	
50	2	100	150	245	265	15	
		160					
80	3	250	120	265	290	18	
		400					
100	4	400	150	260	206	25	
100	4	650	150	260	306	25	
		650					
150	6	1000	175	320	330	40	
		1600					
200	8	1600	200	370	365	55	
200	0	2500	200	370	305	55	
250	10	2500	300	420	400	PN 10 = 60	
250	10	4000	300	430	400	PN 25 = 75	
200	12	4000	200	600	410	PN 25 = 103	
300	12	6500	300	600	410	PN10 = 86	
		6500				PN10 = 190	
400	16	10000	600	640	420	PN16 = 210	
		10000				PN40 = 300	

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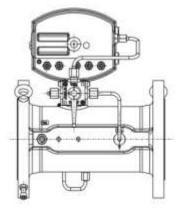
# RMG<sup>•</sup>

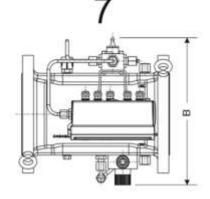
### TME400-VMF

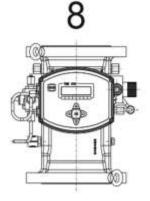
Front view



**Rear side** 







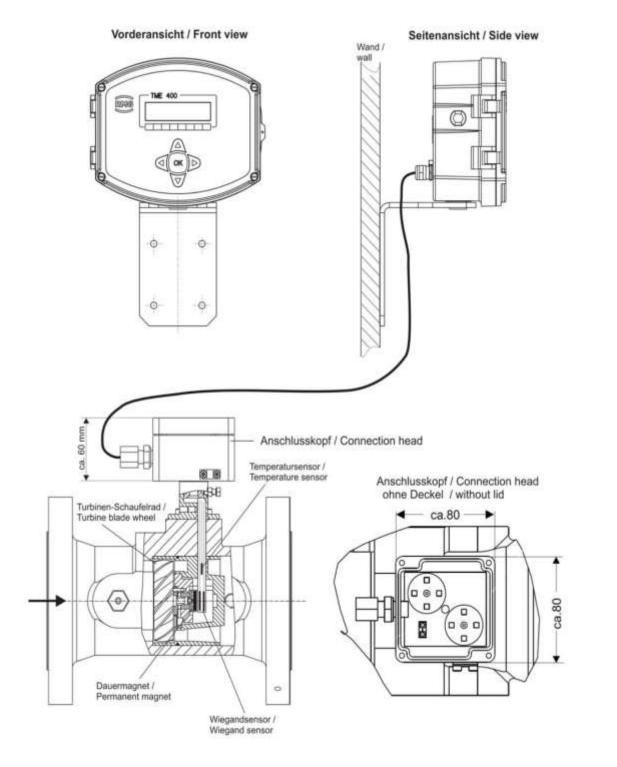
- 1 -
- 2 Oil pump
- 3
- 4 -

- 5 -
- 6 -
- 7 Top view
- 8 Top view for flow direction from bottom top up to DN200



Size			Max. Flow rate	Dimensions		Weight		
			Qmax					
mm	Inch	G-Size	m3/h	Length L	Width B	Hight H	kg	
50	2	G65	65	150	320	310	15	
		G100	160					
80	3	G160	250	240	270	250	20	
		G250	400					
		G160	250					
100 4		G250	400	300	285	254	28	
		G400	650					
			650		310	280		
150 6		G650	1000	450			50	
		G1000	1600					
200	8	G1000	1600	600	380	320	100	
200	0	G1600	2500	000	500	520	100	
		G1000	1600				ANSI150 = 160	
250	10	G1600	2500	750		345	PN16 = 150	
		G2500	4000				PN10 = 150	
		G2500	4000				ANSI150 = 250	
300	12	G4000	6500	900		360	PN16 = 215	
		G4000-45	6500**				PN10 = 210	

#### **Remote meter**



Cable length:10 mPressure sensor:integrated in the connection headHeight:approx. 80 mm less than the "normal" height (see above)



# D Measuring ranges for TME 400-VMF/ TME 400-VCF

Values for custody transfer metering according to MID approval with natural gas

102																	
	DN	G-	Q <sub>max</sub>		low [m <sup>3</sup> /h] Q <sub>min</sub> [m <sup>3</sup> /h] depending on operating pressure p <sub>min</sub> [bar(g)] t p <sub>min</sub> =1 bar <sup>[1]</sup>												
	[mm]	value	[m³/h]	at p <sub>min</sub> = MR <sup>[2]</sup>		MR 1:30		MR 1:50		MR 1:80		MR 1:100		MR 1:120		MR 1	:160
				Qt	Q <sub>min</sub>	Q <sub>min</sub>	Pmin	Q <sub>min</sub>	p <sub>min</sub>	Q <sub>min</sub>	p <sub>min</sub>	Q <sub>min</sub>		Q <sub>min</sub>	p <sub>min</sub>	Q <sub>min</sub>	p <sub>min</sub>
	50	65	100	20	5 <sup>[3]</sup>												
		100	160	32	8[3]	5	15	3,2	50								
	80	160	250	50	12,5	8	3	5	10	3,2	50						
		250	400	80	20	13	3	8	10	5	25						
		160	250	50	12,5	8	3	5	25								
	100	250	400	80	20	13	3	8	10	5	25						
		400	650	130	32	20	3	13	4	8	10	6,5	15	5	25		
		400	650	130	32	20	3	13	10	8	25	6,5	40				
	150	650	1000	200	50	32	3	20	4	13	10	10	15	8	25		
		1000	1600	320	80	50	3	32	4	20	10	16	15	13	25	10	40
	200	1000	1600	320	80	50	3	32	4	20	10	16	15	13	25	10	40
	200	1600	2500	500	125	80	3	50	4	32	10	25	15	20	25	16	40
		1000	1600	320	80	50	3	32	10	20	25	16	40				
	250	1600	2500	500	125	80	3	50	4	32	10	25	25	20	40	16	60
		2500	4000	800	200	130	3	80	4	50	10	40	25	35	40	25	60
		2500	4000	800	200	130	3	80	4	50	10	40	25	35	40	25	60
	300	4000	6500	1300	320	220	3	130	10	80	25	65	40	55	60	40	80
		4000-45	6500	1300	320	220	3	130	10	80	25	65	40	55	60	40	80

 $^{[1]}$  p = 1 bar; means atmospheric pressure

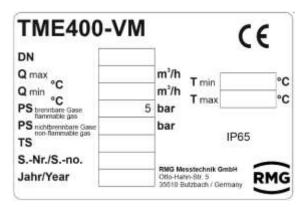
<sup>[2]</sup> MR = Measuring range =  $Q_{max} / Q_{min}$ 

<sup>[3]</sup> MR: 1:20; for  $p \ge 3$  bar(g)

# RMG

# E Type plate

Main type plate TME400-VM for DN25, for Non-Ex, no custody transfer applications



Main type plate TME400-VM from DN40, for Non-Ex, no custody transfer applications

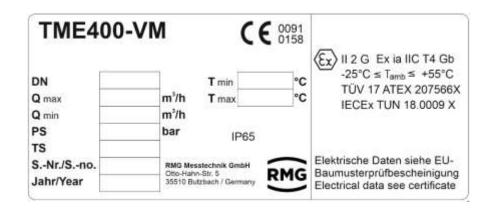
TME400-	VM CE	0091
DN Q max	T min m³/h T max	°C ℃
Q min	m³/h	
PS	bar IP65	
TS		
SNr./Sno. Jahr/Year	RMG Messtechnik GmbH Otto-Hahn-Str. 5 35510 Butzbach / Germany	RMG



Main type plate TME400-VM for DN25, for Ex, no custody transfer applications

TME400-\	/M	(	€ 0158	
DN				Ex II 2 G Ex ia IIC T4 Gb
Q max		m³/h T min	°C	$-25^{\circ}C \le T_{amb} \le +55^{\circ}C$
Q min		m <sup>3</sup> /h T max	°C	TÜV 17 ATEX 207566X
PS bronnbare Gase	5	bar	C	IECEx TUN 18.0009 X
PS nichtbrennbere Gase		bar IPi	25	
TS		15	55	
SNr./Sno.		RMG Messtechnik GmbH	-	Elektrische Daten siehe EU-
Jahr/Year		Otto-Hahn-Str. 5 36510 Butzbach / German	RMG	Baumusterprüfbescheinigung Electrical data see certificate

Main type plate TME400-VM from DN40, for Ex, no custody transfer applications



# RMG

12:40

105

# F Seal diagrams

The following figures show the positions of the seals on the TME400.

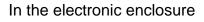
Front side

Back side



Security seal Sicherheitsplombe

Seal cap with lead seal Siegelkappe mit Bleiplombe



### At the connection head





# G Later installation of the power module

## **A** Caution

The power module must only be installed in a de-energized state.

In order to switch of any power supply the battery must be removed (see *chapter 3.1.4 Battery replacement*) and any external supply voltage must be switched off, i.e. in the case of an external supply, the wires from terminals X6 / +Uext and X6 / -Uext must be removed.

The power module (3) must be plugged on as shown in *Figure 19: Electronic with power module*. The current module is factory adjusted and <u>does not need</u> to be calibrated before operation.



Figure 19: Electronic with power module

- 1 Jumper for RS 485 terminating resistor. Bridged: with 120  $\Omega$ ; open:  $\infty \Omega$
- 2 Calibration switch
- 3 Current module board
- 4 Cover plate for pressure and temperature sensor and calibration switch
- 5 Normal position, indicated by green arrows

### Putting the power module into operation

After reconnecting the TME400 supply voltages, the current loop power supply must be connected to X9 and the current output parameterized.

# **A** Caution

The voltages of the current loop and the external supply must be electrically isolated (galvanically isolated see *chapter 2.1 Electrical connections*, especially the connection drawings in the Ex- /Non-Ex area at the end of the chapter).

107

### Parameterization of the current module

To complete the installation, various parameters must be checked or configured. To do this, the parameter protection must be removed, either by entering the code word (see *chapter 4.3.3.7 Settings*) or by pressing the calibration button (see *Figure 19: Electronic with power module*).

- 1. First the date and time must be entered in the coordinates X1 and X2
- 2. The current output parameters F02, F03, F04, F05 (see *chapter 4.3.3.3 Current output*) must then be parameterized according to the application.

For example, a typical parameterization may look like this:

F02:	1	Without error
F03:	1	Operating flow rate
F04:	0	i.e. $4 \text{ mA} = 0 \text{ m}^3/\text{h}$
F05:	200	i.e. 20 mA = 200 m <sup>3</sup> /h

For testing, F03 can be set to 0 (default) and a current value in the range of 4 - 20mA can be selected with F06.



# **H** Spare parts and accessories

Order number Description

### **Mechanical components**

84.08.021.00	Check valve compl. RHD06L3BLUFTCF
90.59.266.00	Piston pump+adjusting screw+oil tank
00.66.960.00	Remote totalizer

# **Elektronical components**

98800-16590	NonEx TME current module 4-20mA passive
38.02.016.00	EExi supply f.4-20mA current output
86.98.211.01	Power supply 24V/DC 1.4A surface mounted
86.98.249.00	Ex-i power supply 24 V
30.00.619.00	Transmitter power supply KFD2-STC5-1
30.00.733.00	Transmitter power supply KFD2-STC5-Ex1
35.00.013.00	Isolating amplifier TURCK IM1-12-T
30.00.019.00	Interface/pulse separating module Datcom K3
35.00.000.00	PS (230V/AC - 12V/DC) for K3 module
86.76.553.00	OMRON DC/DC adapter for Datcom K3

# Expendable materials

92102-00200	Power supply battery
38.11.148.01	Lubricant 2-4°E/20°C TRZ/DKZ 1L
38.11.148.05	Lubricant 2-4°E/20°C TRZ/DKZ 5L

# RMG

# I Certificates and approvals

The **TME400** is approved for custody-transfer measurements. Approvals are available for operation in hazardous environments and for the Pressure Equipment Directive, which are provided as copies in the appendix.

1. EU Declaration of Conformity	109
2. NMI Evaluation Certificate	109
3. ATEX	
4. IECEx	
<ol><li>EU-Type Examination Certificate Directive 2014/34/EU</li></ol>	
6. PED Module D	
7. EU-Type Examination Certificate Module B Directive 2014/68/EU	
8. Production Quality Assurance	









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N	<b>N</b> t)			uation	
-~			Certi	ficate	
				<b>11907</b> revision 0 nber 2249056	111
issued	by NMi Certin	B.V.,		_	<b>_</b>
In acco	System o - Europea	5.8 "General and Administr of Modular Evaluation of Me n Standard EN 12405-1:2005 - Part 1: volume conversion".	asuring instruments +A2:2010 "Gas mete	under the MID"	
Produc	cer RMG Messt Otto-Hahn- 35510 Butzi Germany				
Part		ng and indicating device, as-volume conversion device			
	Туре	+	TME400-VCF TME400-VMF	(config. 1a/1b*) (config. 2a/2b*)	
	Manufactur	er's mark or name :	RMG		
	Conversion	이 집에 가장 아직 아직 것 같아. 이 있 ?	T, PT or PTZ None (* see de –25 °C / +55 °C Condensing and r humidity	8	
	Environmer The intende	it classes : ed location for the instrumen	M2 / E2 t is open.		
	- Descriptio	perties are described in the a n TC11907 revision 0; tation folder TC11907-1.	nnexes:		
Issuing	Authority NMi Certin 4 September	B.V., Notified Body numb 2020	er 0122	(+)	
	Certification	Board		_	
Thipseve     2629 JA 0     The Nath	g 11 that no liability is helft manufacturer sha	accepted and that the document Il indemnify third-party	ion of the complete only is permitted. nent is digitally signed and	RJN	
T+3188 certification	636 2332 mi.nl The designation o i.nl Notified Body can	of NMi Certin B.V. as verified in	e digital signature can be the blue ribbon at the top tronic version of this	INSPECTION BVA   122	

112



	NAT	EU-ty	pe examination
			certificate
			Number <b>T11741</b> revision 0 Project number 2341823 Page 1 of 1
(+	issued by	conformity modules mentioned	Netherlands to perform tasks with respect to in article 17 of Directive 2014/32/EU, after suring instrument meets the applicable 12/EU, to:
	Manufacturer	RMG Messtechnik GmbH Otto-Hahn-Strasse 5 D-35510, Butzbach Germany	
	Measuring instrument	A <b>Turbine Gas Meter with op</b> Types	tional EVCD : TME400-VCF TME400-VMF
124		Manufacturer's mark or name	: RMG Messtechnik
		Destined for the measurement o Accuracy class Turbine meter	f : Gas volume : Class 1,0
		Environment classes Environment temperature range Gas temperature range	: M1/E2 : -25 °C/+55 °C : -25 °C/+55 °C
		Further properties are described – Description T11741 revision 0; – Documentation folder T11741-	
	Valid until	4 September 2030	
	Issuing Authority	NMi Certin B.V., Notified Body	number 0122
		4 September 2020 Certification Board	
۲	NMi Certin B.V. Thijaseweg, 11 2629 JA Delft The Netherlands T + 31 B8 56 2332 certinthum of ywww.mmi.ol	This document is issued under the provision that no iiability is accepted and that the manufacturer shall indemnify third-party liability. The designation of NMI Certin 0.V as Notified Body can be verified at https/ e.ceuropa.eu/growth/bods-databaces/nando/	Reproduction of the complete document only is permitted. This document is digitally signed and sealed. The digital granture can be verified in the blue ribbon at the top of the electronic version of this corrificate.







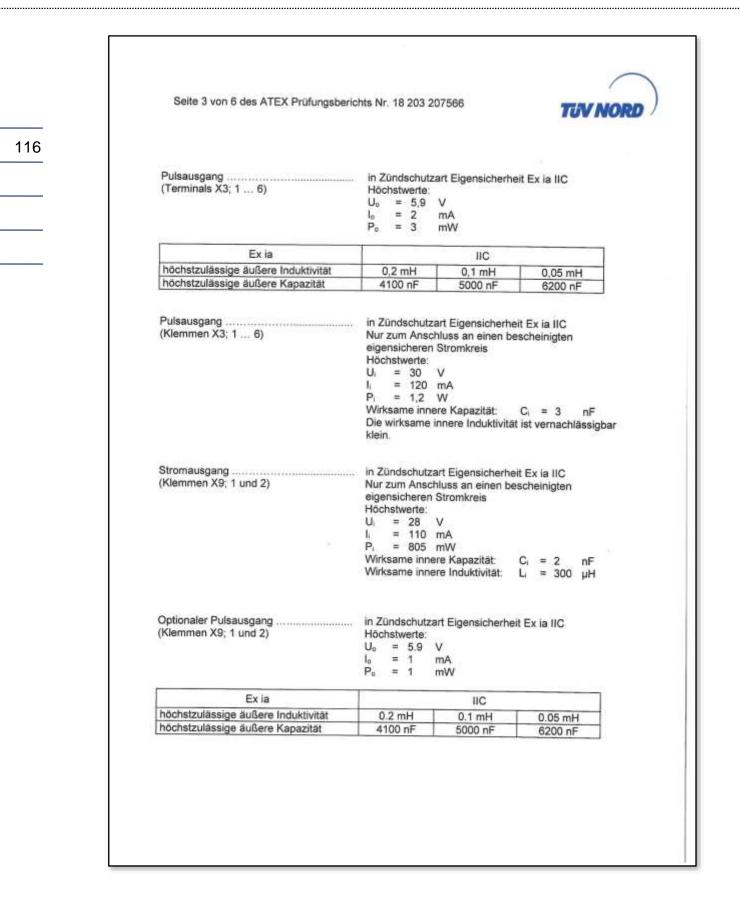
TÜV NORD CERT GmbH Langemarckstr 20 45141 Essen		TUV NOR Zertifizierun
ATEX Prüfungsberic	ht	18 203 207566 vom 05.07.2018
Auftraggeber:	RMG Messtechnik G Otto-Hahn-Straße 5 35510 Butzbach	mbH
Auftragsnummer:	8000476316	
ZA Nummer:	35207566	
Prüfgegenstand:	Elektronischer Gasm	engenumwerter Typ VC, VM, VCF, VMF
Beurteilungsgrundlagen:	EN 60079-0:2012 +A11:2013	Allgemeine Bestimmungen
	EN 60079-11:2012	Geräteschutz durch Eigensicherheit "i"
Prüflabor:	TÜV NORD CERT G Büro Hannover Am TÜV 1 30519 Hannover	h
Ort der Prüfung:	Siehe oben	
Eingangsdatum des Prüfgegenstandes:	H/2017/2341 und H/2	2018/2384
Datum der Prüfung:	bis 05.07.2018	
Interpretationen:		stätigt die Übereinstimmung des Gerätes mit der oben genannten Beurteilungsgrundlagen
Prüfung; /		Fachzertifizierung:
Jak		Ch
Klaus Hoferichter		Anke Drews
Dieser Bericht umfasst 6 Se	iten	Januarian and a start of the st
	/	
	/	
Dieser technische Bericht stellt das Er Aussage über die Qualität der Produkt Vervielfältigung dieses technischen Be Prüflaboratoriums.	gebnis der Prüfung an dem vor te aus der laufenden Fertigung arichts und die Verwendung zu	rgestelten Prüfgegenstand dar. Eine allgemein gültige kann daraus nicht abgeleitet werden. Die auszugsweise Werbezwecken bedürfen der schriftlichen Genehmigung des
P17-F-100 06.15		

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Seite 2 von 6 des ATEX Prüfungsberic	hts Nr. 18 203 2	07566	7	TUV NO	RD)	
<ol> <li>Auftragsbeschreibung: Prüfung des Gerätes "Elektronischer Gasr Ausstellen einer EU-Baumusterprüfbesch</li> </ol>	mengenumwerte einigung und eir	er TME 400 Typ V	/C, VM, VC	F, VMF* un	d	_
2. Spezifikation des Prüfgegenstandes: Der elektronische Gasmengenumwerter T Verwendung in durch Gas explosionsgefä Es dient zur Gasmessung, Steuerung und und Volumenimpulsen.	: ME 400 Typ VC, ihrdeten Bereich	, VM, VCF, VMF i	ist ein Gerä	ät zur	ur	-
Der zulässige Umgebungstemperaturbere	ich beträgt -25 °	C 55 *C.				-
Elektrische Daten	850888888889999999999999999999999999999					
Versorgungsstromkreis (Terminal X6; 2 and 3)	Nur zum Ansci eigensicheren Höchstwerte: $U_i = 10,7V$ $I_i = 219$ m. $P_i = 325$ m! Wirksame inne	iA iW	escheinigte C. = 7	n		
Versorgungsstromkreis Batterie, intem (Steckverbinder X12; 1 und 2)	Saft, type LS33	u interner Batterie 13600, 17 Ah oder L 205-F, 19 Ah				
Signaleingang (Klemmen X6; 4 und 5)	Höchstwerte: $U_0 = 5.9$ $I_0 = 3$	mA mW	it Ex ia IIC			
Ex ia		IIC				
höchstzulässige äußere Induktivität	0.2 mH	0.1 mH	0.05 r			
höchstzulässige äußere Kapazität	4100 nF	5000 nF	6200			
RS 485 und Signaleingang (Klemmen X6; 6 und 7)	Höchstwerte: U <sub>0</sub> = 5,9	mA mW	it Ex ia IIC			
Exia		IIC				
höchstzulässige äußere Induktivität höchstzulässige äußere Kapazität	1.7 mH	0.7 mH	0.2 m			
nounstaulassige ausere rapazitat	2100 nF	2600 nF	3100	nF		









Seite 4 von 6 des ATEX Prüfungsberic	hts Nr. 18 203 2	07566	TUVA	VORD)	
Impulseingang Reed/Wiegand, intern (Klemmen X5; 1 4)	Höchstwerte: U <sub>o</sub> = 5,9	V mA mW	heit Ex ia IIC		-
Exia		lic		1	
höchstzulässige äußere Induktivität	20 mH	10 mH	Embl	-	
höchstzulässige äußere Kapazität	1800 nF	1900 nF	5 mH 2100 nF	-	
	l₀ = 100 P₀ = 148 Kennlinie: linea	mW			
Ex ia		lic		ĺ.	
höchstzulässige äußere Induktivität	30 µH		25 µH		
höchstzulässige äußere Kapazität Sensor	4100 nF UTC30		2000 nF TI-1		
(Klemmen X11; 1 und 2)	Höchstwerte: U <sub>0</sub> = 5,9 I <sub>0</sub> = 9 P <sub>0</sub> = 13 Kennlinie: linea	mA mW			
Exia	the finance arrow			1	
höchstzulässige äußere Induktivität	0.5 mH	IIC 0.2 mH	0.1		
höchstzulässige äußere Kapazität	3200 nF	0.2 mH 4000 nF	0.1 mH 4900 nF		
Alle Höchstwerte L <sub>o</sub> and C <sub>o</sub> Werte dürfe ausgenutzt werden. Aus sicherheitstechnischer Sicht sind alle e GND-Potential verbunden und sicher galva Bei der Zusammenschaltung von eigensicheren St Zusammenschaltung von eigensicheren St B. Kennzeichnung des Prüfgegenstande Ex II 2 G Ex ia IIC T4 Gb	eigensicheren Str anisch vom Erdpo heren Stromkreis romkreisen zu be	romkreise galva otential getrennt en sind die Reg eachten.	anisch miteinander ü t. glen für die	211012241	
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98800-17002 98800-17002	· · · · · · · · · · · · · · · · · · ·	Rev. Stand:	Datum:
98800-17002	Turbine Meter Electronic WIKA Drucksensor Adapter	2	2018-05-15
	Parts list	-	2018-06-27
98800-17002	Turbine Meter Electronic TME 400 Wika Adapter (8 Seiten)	2	2018-05-15 and 2018-04-11
98800-16991	Turbine Meter Electronic	1	2017 10 05
98800-16992	Backlight Parts list		2017-10-25
98800-16992	Turbine Meter Electronic TME 400 Beleuchtung (5 Seiten)	2	2018-04-16 2018-04-10
PCB NO.: 91101-06722	Turbine Meter Electronic Electronic Abdeckung Top Assembly Drawing	2	2018-04-12
Luftfeuchtigkeit: Nicht	erforderlich		
	Ende des ATEX Prüfungsberichtes		
		-	2
		-	27
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Certificate No.: IECEx TUN 18.0009X Status: Current Date of Issue: 2018-07-25 Applicant: PMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach Germany Equipment: Electronic gas value corrector TME400 type V Optional accessory: Type of Protection: Intrinsic Safety T Marking: Ex ia IIC T4 Gb Approved for issue on behalf of the IECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	e for Explosive Atm CEx Scheme visit www.iecex.cc	PMMISSIC loopheres	DN .
IEC Certification Scheme Iter rules and details of the E         Certificate No.:       IECEx TUN 18.0009X         Status:       Current         Date of Issue:       2018-07-25         Applicant:       RMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach Germany         Equipment:       Electronic gas value corrector TME400 type V Optional accessory:         Type of Protection:       Intrinsic Safety "F Marking:         Ex is IIC T4 Gb       Approved for issue on behalf of the IECEx Certification Body:         Position:       Signature: (for printed version)         Date:       1. This certificate and schedule may only be reproduced in full.         1. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visit         Certificate issued by:         TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	Frank Hiller	Issue No: 0 Page 1 of 3	Certificate history:
Status:       Current         Date of Issue:       2018-07-25         Applicant:       RMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach Germany         Equipment:       Electronic gas value corrector TME400 type V Optional accessory:         Type of Protection:       Intrinsic Safety T* Marking:         Ex is IIC T4 Gb         Approved for issue on behalf of the IECEx Cartification Body:         Position:         Signature: (for printed version)         Date:         1. This certificate and schedule may only be reproduced in full.         2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visit         Certificate issued by:         TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	rC, VM, VCF, VMF Frank Hiller	Page 1 of 3	the state of the s
Date of Issue: 2018-07-25 Applicant: RMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach Germany Equipment: Electronic gas value corrector TME400 type V Optional accessory: Type of Protection: Intrinsic Safety T Marking: Ex ia IIC T4 Gb Approved for issue on behalf of the IECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	/C, VM, VCF, VMF Frank Hiller		
Applicant:       RMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach Germany         Equipment:       Electronic gas value corrector TME400 type V Optional accessory:         Type of Protection:       Intrinsic Safety T Marking:         Ex ia IIC T4 Gb         Approved for issue on behalf of the IECEx Certification Body:         Position:         Signature: (for printed version)         Date:         1. This certificate and schedule may only be reproduced in full.         2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visit         Certificate issued by:         TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	/C, VM, VCF, VMF Frank Hiller		
Otto-Hahn-Straße 5 35510 Butzbach Germany Equipment: Electronic gas value corrector TME400 type V Optional accessory: Type of Protection: Intrinsic Safety T Marking: Ex ia IIC T4 Gb Approved for issue on behalf of the IECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	Frank Hiller	ification Body	
Optional accessory: Type of Protection: Intrinsic Safety " Marking: Ex is IIC T4 Gb Approved for issue on behalf of the IECEx Certification Body: Position: Signsture: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	Frank Hiller	ification Body	
Type of Protection: Intrinsic Safety T Marking: Ex is IIC T4 Gb Approved for issue on behalf of the IECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		ification Body	
Marking: Ex is IIC T4 Gb Approved for issue on behall of the IECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		ification Body	
Ex ia IIC T4 Gb Approved for issue on behalf of the JECEx Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		ification Body	
Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		ification Body	
Certification Body: Position: Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate and schedule may only be reproduced in full. 2. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		ification Body	
Signature: (for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	Deputy Head of the Cert	ification Body	
(for printed version) Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover			
Date: 1. This certificate and schedule may only be reproduced in full. 2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by vision Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover			
This certificate and schedule may only be reproduced in full.     This certificate is not transferable and remains the property of the is     The Status and authenticity of this certificate may be verified by visi     Certificate issued by:     TÜV NORD CERT GmbH     Hanover Office     Am TÜV 1, 30519 Hannover			
2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover	-		
2. This certificate is not transferable and remains the property of the is 3. The Status and authenticity of this certificate may be verified by visi Certificate issued by: TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover			
TÜV NORD CERT GmbH Hanover Office Am TÜV 1, 30519 Hannover		sile	
Am TÜV 1, 30519 Hannover			
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Germany	THE MOD		
	<b>TUV NOR</b>		



	×	ECEx Certificate	
		of Conformity	
Certificate No:	IECEx TUN 18.0009X	Issue No: 0	
Date of Issue:	2018-07-25	Page 2 of 3	1
Manufacturer:	RMG Otto-Hahn-Straße 5 35510 Butzbach Germany		
Additional Manufacturing loca	ation(s):		
EC Standard list below and t ound to comply with the IEC	hat the manufacturer's quality system, relati	f production, was assessed and tested and found to comply with the ng to the Ex products covered by this certificate, was assessed and ate is granted subject to the conditions as set out in IECEx Scheme	
STANDARDS:			
The apparatus and any acce with the following standards:	ptable variations to it specified in the schedu	le of this certificate and the identified documents, was found to comply	
EC 60079-0 : 2011 Edition:6.0	Explosive atmospheres - Part 0: Gen	reral requirements	
EC 60079-11 : 2011 Edition:6.0	Explosive atmospheres - Part 11: Eq	uipment protection by intrinsic safety "f"	
This Certificate does not in	dicate compliance with electrical safety and	performance requirements other than those expressly included in the	
	Standards lis	ited above.	
EST & ASSESSMENT REP	ORTS:		
	t listed has successfully met the examination	n and lest requirements as recorded in	
fest Report:			
DE/TUN/ExTR18.0018/00			
Quality Assessment Report:			
DE/BVS/QAR08.0011/07			



IEC TEC	Ex	ECEx Certificate
		of Conformity
Certificate No:	IECEx TUN 18.0009X	Issue No: 0
Date of Issue:	2018-07-25	Page 3 of 3
	Sched	ule
EQUIPMENT: Equipment and systems of	overed by this certificale are as follows:	
The electronic gas value co	rrector TME400 type VC, VM, VCF is an appara	utus for use in gas explosion hazardous areas.
It is used for gas measuring	, control and regulating purposes by detection of	of pressure, temperature and volume pulses.
The permissible ambient ter	nperature range is -25 °C 55 °C.	
See attachment for details.		
SPECIFIC CONDITIONS	OF USE: YES as shown below:	
1.Electrostatic charge has to	be avoided for all housing parts. The warning	label has to be observed.
2. The earth terminal hast to	be connected with the potential equalization in	the explosion hazardous area.
Annex:		





TÜV NORD CERT GmbH Hannover Office Am TÜV 1				
30519 Hannover			TUV NORD	
Germany			Zertifizierung	-
	Dans 4 of 4		20. United only	
Attachment to	Page 1 of 4 IECEx TUN 18.0		.: 0	
Product:				-
The electronic gas value corrector TME 40 gas explosion hazardous areas. It is used for gas measuring, control and n temperature and volume pulses.	2000.02.0801012.000.002			
The permissible ambient temperature range	ge is -25 °C 5	5 °C.		
Electrical data				
Supply circuit (Terminal X6; 2 and 3)	Only for conner Maximum value U <sub>i</sub> = 10.7 V I <sub>i</sub> = 219 m P <sub>i</sub> = 325 m Effective intern	es: nA	d intrinsically safe circuit C <sub>1</sub> = 7 nF	
Supply circuit battery, internal (Plug connector X12; 1 and 2)	connection to in Saft, type LS33 XENO, type XL	3600, 17 Ah or		
Signal input (Terminals X6; 4 and 5)	Maximum value U <sub>o</sub> = 5.9 I <sub>o</sub> = 3	V mA mW	fety Ex ia IIC	
Ex ia		IIC		
max. permissible external inductance max. permissible external capacitance	200 µH 4100 nF	100 µH 5000 nF	50 µH 6200 nF	

124



Page 2 of 4 Attachment to IECEx TUN 18.0009 X issue No.: 0RS 485 and signal inputin type of protection Intrinsic Safety Ex ia life Maximum values: $U_o = 5.9 \ V$ $I_o = 60 \ mA$ $P_o = 88 \ mW$ Characteristic line: linearImax. permissible external inductance1700 $\mu$ H700 $\mu$ HRS 485 and signal input11Cmax. permissible external inductance1700 $\mu$ H700 $\mu$ HRS 485 and signal inputin type of protection Intrinsic Safety Ex ia life Only for connection to a certified intrinsically Maximum values: $U_i = 10.7 \ V$ $I_i = 219 \ mA$ $P_i = 325 \ mW$ Effective internal inductance:C, = 2.1 Effective internal inductance:Lifective internal inductance:Li = 300
(Terminals X6; 6 and 7)Maximum values: $U_o = 5.9 V$ $I_o = 60 mA$ $P_o = 88 mW$ Characteristic line: linearEx iaIICmax. permissible external inductance1700 µH700 µHmax. permissible external capacitance2100 nF2600 nFRS 485 and signal inputin type of protection Intrinsic Safety Ex ia IIC Only for connection to a certified intrinsically Maximum values: $U_i = 10.7 V$ $I_i = 219 mA$ $P_i = 325 mW$ Effective internal capacitance: $C_i = 2.1$
$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$
max. permissible external capacitance $2100 \text{ nF}$ $2600 \text{ nF}$ $3100 \text{ nF}$ RS 485 and signal inputin type of protection Intrinsic Safety Ex ia III Only for connection to a certified intrinsically Maximum values: $U_i = 10.7 \text{ V}$ $I_i = 219 \text{ mA}$ $P_i = 325 \text{ mW}$ Effective internal capacitance: $C_i = 2.1$
RS 485 and signal input (Terminals X6; 6 and 7) $U_i = 10.7 V$ $U_i = 325 mW$ Effective internal capacitance: $C_i = 2.1$
Pulse output
Ex ia IIC
max, permissible external inductance 200 µH 100 µH 50 µH
max. permissible external capacitance       4100 nF       5000 nF       6200 nF         Pulse output       in type of protection Intrinsic Safety Ex ia III0       Only for connection to a certified intrinsically Maximum values: Ui       = 30 V       V         Ui       = 30 V       V       Effective internal capacitance:       Ci       = 3         The effective internal inductance is negligible       The effective internal inductance is negligible       Ci       = 3





Hannover Office Am TÜV 1 30519 Hannover Germany			TUV NORD Zertifizierung
Attachment to	Page 3 of 4 IECEx TUN 18.	i 0009 X issue No	: 0
Current output (Terminals X9; 1 and 2)	Only for conne Maximum valu U <sub>i</sub> = 28 I <sub>i</sub> = 110 P <sub>i</sub> = 805 Effective interr	es: V mA mW al capacitance:	I intrinsically safe circuit
Optional pulse output (Terminals X9; 1 and 2)	$\begin{array}{llllllllllllllllllllllllllllllllllll$		fety Ex ia IIC
Ex ia	-	IIC	
max. permissible external inductance	200 µH	100 µH	50 µH
max. permissible external capacitance	4100 nF	5000 nF	6200 nF
Impulse input Reed/Wiegand, internal	in type of prote Maximum valu U <sub>o</sub> = 5.9		fety Ex ia IIC
(Terminals X5; 1 4) Ex ia	I <sub>o</sub> = 6 P <sub>o</sub> = 8 Characteristic	mA mW line: linear IIC	1
Exia	l <sub>o</sub> = 6 P <sub>o</sub> = 8	mW line: linear	5 mH
	I <sub>o</sub> = 6 P <sub>o</sub> = 8 Characteristic	mW line: linear IIC	5 mH 2100 nF
Ex ia max. permissible external inductance	I <sub>o</sub> = 6 P <sub>o</sub> = 8 Characteristic 20 mH 1800 nF	mW line: linear IIC 10 mH 1900 nF ection Intrinsic Sa es: V mA mW	2100 nF
Ex ia max. permissible external inductance max. permissible external capacitance Pressure sensor circuit, internal (Terminals X8; 1 4) Ex ia	$\begin{array}{rcl} I_{o} &=& 6\\ P_{o} &=& 8\\ Characteristic\\ \hline \\ \hline 20 \text{ mH}\\ 1800 \text{ nF}\\ \hline \\ 1800 \text{ nF}\\ \hline \\ in type of prote \\ Maximum valu \\ U_{o} &=& 5.9\\ I_{o} &=& 100\\ P_{o} &=& 148\\ Characteristic\\ \hline \end{array}$	mW line: linear IIC 10 mH 1900 nF ection Intrinsic Sa es: V mA mW	2100 nF
Ex ia max. permissible external inductance max. permissible external capacitance Pressure sensor circuit, internal (Terminals X8; 1 4) Ex ia max. permissible external inductance	$\begin{array}{rcl} I_{o} &=& 6\\ P_{o} &=& 8\\ Characteristic\\ \hline \\ \hline \\ 20 \text{ mH}\\ \hline \\ 1800 \text{ nF}\\ \hline \\ \hline \\ in type of prote \\ Maximum valu \\ U_{o} &=& 5.9\\ I_{o} &=& 100\\ P_{o} &=& 148\\ Characteristic\\ \hline \\ \hline \\ 30  \mu\text{H} \end{array}$	mW line: linear IIC 10 mH 1900 nF ection Intrinsic Sa es: V mA mW line: linear IIC	2100 nF fety Ex ia IIC 25 µH
Ex ia max. permissible external inductance max. permissible external capacitance Pressure sensor circuit, internal (Terminals X8; 1 4) Ex ia	$\begin{array}{rcl} I_{o} &=& 6\\ P_{o} &=& 8\\ Characteristic\\ \hline \\ \hline 20 \text{ mH}\\ 1800 \text{ nF}\\ \hline \\ 1800 \text{ nF}\\ \hline \\ in type of prote \\ Maximum valu \\ U_{o} &=& 5.9\\ I_{o} &=& 100\\ P_{o} &=& 148\\ Characteristic\\ \hline \end{array}$	mW line: linear IIC 10 mH 1900 nF ection Intrinsic Sa es: V mA mW line: linear IIC	2100 nF

126

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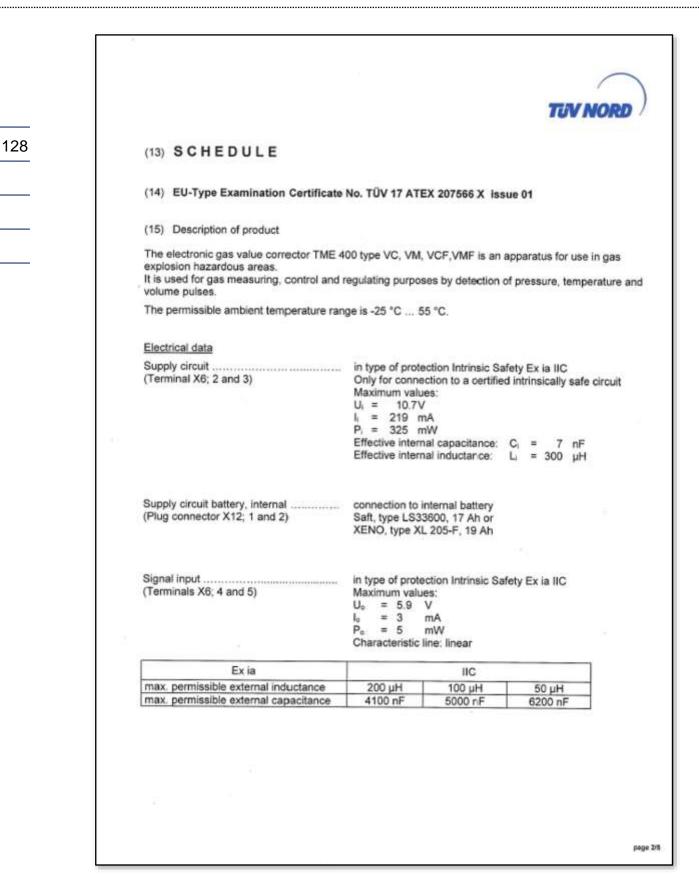


TÜV NORD CERT GmbH Hannover Office Am TÜV 1 30519 Hannover Germany		1	<b>Tự NO</b> Zertifizi
Attachment	Page 4 of 4 to IECEx TUN 18.0		: 0
Pt1000 temperature input, internal (Terminals X11; 1 and 2)	Maximum valu U <sub>e</sub> = 5.9 I <sub>e</sub> = 9	V mA mW	fety Ex ia IIC
Exia		lic	
max. permissible external inductance	500 µH	200 µH	100 µH
max. permissible external capacitance	3200 nF	4000 nF	4900 nF
At interconnection of intrinsically safe of circuits have to be observed.	eparated from eart	h potential.	
At interconnection of intrinsically safe of		h potential.	
At interconnection of intrinsically safe of circuits have to be observed.	ircuits, the rules for	h potential.	of intrinsically s
At interconnection of intrinsically safe of circuits have to be observed. Special Conditions for Safe Use: 1. Electrostatic charge has to be avoid	ircuits, the rules for ed for all housing pa	h potential. interconnection of arts. The warning	label has to be
At interconnection of intrinsically safe of circuits have to be observed. <u>Special Conditions for Safe Use:</u> 1. Electrostatic charge has to be avoid observed. 2. The earth terminal hast to be connect	ircuits, the rules for ed for all housing pa	h potential. interconnection of arts. The warning	of intrinsically so
At interconnection of intrinsically safe of circuits have to be observed. <u>Special Conditions for Safe Use:</u> 1. Electrostatic charge has to be avoid observed. 2. The earth terminal hast to be connect	ircuits, the rules for ed for all housing pa	h potential. interconnection of arts. The warning	of intrinsically s label has to be



			(	
			/	
(1)	Translation EU-Type Exam	ination Certificate	<b>T</b> iv Nord	
(2)	Equipment and protective intended for use in potent explosive atmospheres, D	tially	(Ex)	1
(3)	Certificate Number	TÜV 17 ATEX 207566 X	issue: 01	
(4)	for the product:	Electronic gas value correct type VC, VM, VCF, VMF	or TME 400	_
(5) (6)	of the manufacturer: Address:	RMG Messtechnik GmbH Otto-Hahn-Straße 5 35510 Butzbach		
	Order number:	8003000905		
	Date of issue:	2019-03-12		
(7)		t and any acceptable variation ther rtificate and the documents therein	reto are specified in the schedule to th a referred to.	is
(8)	Directive 2014/34/EU of that this product has been relating to the design a atmospheres given in Ann	the European Parliament and the an found to comply with the Esse ind construction of products inte	in accordance with Article 17 of th Council of 26 February 2014, certifie ential Health and Safety Requirement ncied for use in potentially explosive ential ATEX Assessment Report	es ts
(9)	Compliance with the Esse with:	ential Health and Safety Requireme	ents has been assured by compliance	6
	EN 60079-0:2012+A11:2	013 EN 60079-11:2012		
(10)	If the sign "X" is placed a	requirements listed at item 18 of t after the certificate number, it indic se specified in the schedule to this	cates that the product is subject to th	ne
(11)	product. Further requiren		esign, and construction of the specifie manufacturing process and supply of	
(12)	The marking of the produ	ct shall include the following:		
	Ex II 2 G Ex ia IIC	T4 Gb		
		gemarckstraße 20, 45141 Essen, notified t 044. legal successor of the TÜV NORD CE	by the central office of the countries for safety ERT GmbH & Co. KG Ident, Nr. 0032	8
	The head of the notified b	ody		
	Hanover office, Am TÜV 1, 305	19 Hannover, Tel. +49 511 998-61455, Fa	x ∽49 511 998-61590	
	This certifi	cate may only be reproduced without any change,	schedule included.	
	Exce P17-F-D11 Rev. 01/04.18	rpts or changes shall be allowed by the TOV NORD	D CERT GmbH page 1	
				374



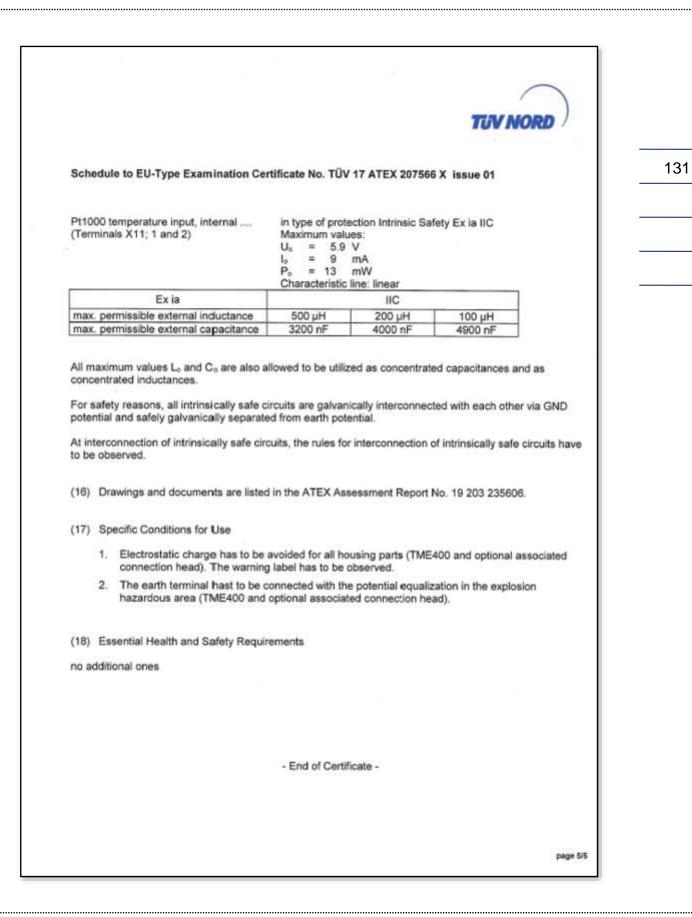




			TUV NO	RD	
Schedule to EU-Type Examination Cer	tificate No. TÜV	17 ATEX 20756	i6 X issue 01		_
RS 485 and signal input (Terminals X6; 6 and 7)	in type of prote Maximum valu $U_0 = 5.9$ $I_0 = 80$ $P_0 = 88$ Characteristic	V mA mW	afety Ex ia IIC		
Ex ia	1	IIC			
max. permissible external inductance	1700 µH	700 µH	200 µH		
max. permissible external capacitance	2100 nF	2600 nF	3100 nF		
Pulse output (Terminals X3; 1 6)	in type of prote Maximum value U <sub>0</sub> = 5.9	nW hal capacitance: hal inductance: ection Intrinsic Sa es:	Cι = 2.1nF L = 300 μH fety Ex ia IIC		
		mW			
Ex ia		IIC			
max. permissible external inductance max. permissible external capacitance	200 µH 4100 nF	100 µH 5000 rF	50 µH 6200 nF		
Pulse output (Terminals X3; 1 6)	Only for connect Maximum value U <sub>1</sub> = 30 I <sub>1</sub> = 120 P <sub>1</sub> = 1.21 Effective interne	es: V mA W al capacitance:	fety Ex ia IIC d intrinsically safe circu C <sub>i</sub> = 3 nF e is negligibly small.	uit	
	Pi = 1.21 Effective interna	W al capacitance:	C <sub>i</sub> = 3 nF e is negligibly small.		

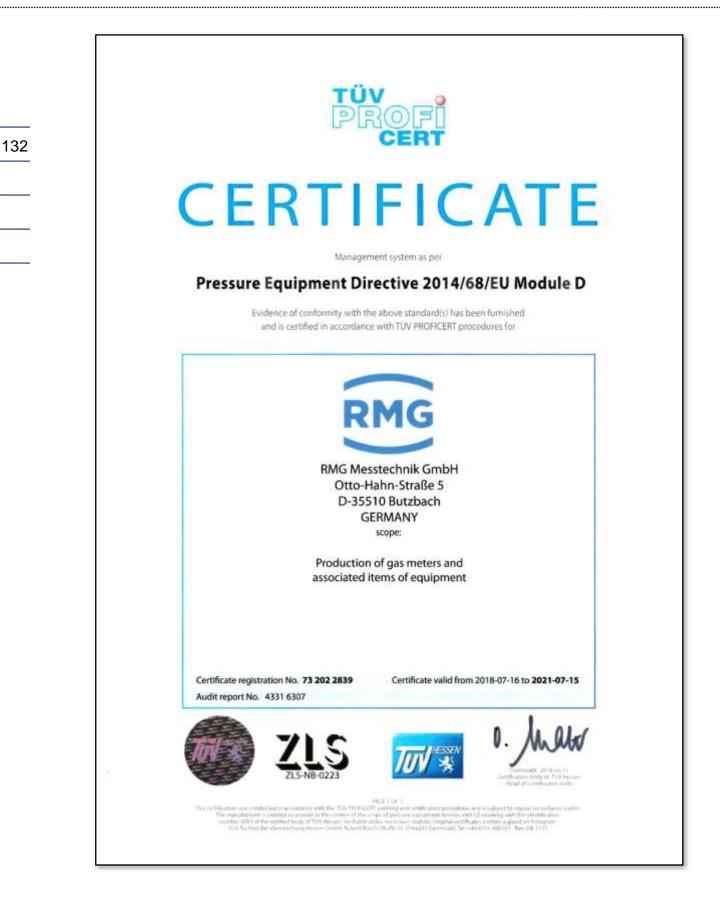


Schedule to EU-Type Examination Cer	tificate No. TÜV 17		TUV
Schedule to EU-Type Examination Cer	tificate No. TÜV 17		
		ATEX 20756	6 X issue 01
An Internet Manager Annual			
Current output (Terminals X9; 1 and 2)	in type of protectio Only for connection Maximum values: U <sub>1</sub> = 28 V I <sub>1</sub> = 110 mA P <sub>1</sub> = 805 mW	n to a certified	d intrinsically saf
	Effective internal c Effective internal in	apacitance: ductance:	C <sub>i</sub> = 2 nF L <sub>i</sub> = 300 μH
Optional pulse output (Terminals X9; 1 and 2)	in type of protectio Maximum values: U <sub>c</sub> = 5.9 V I <sub>c</sub> = 1 mA P <sub>c</sub> = 1 mW		fety Ex ia IIC
Ex ia		IIC	
max, permissible external inductance max, permissible external capacitance	200 µH 4100 nF	100 µH 5000 nF	50 µH 6200 nF
Impulse input Reed/Wiegand, internal (Terminals X5; 1 4)	in type of protectio Maximum values:	n Intrinsic Sal	ety Ex la IIC
	$\begin{array}{rcl} U_{o} &=& 5.9 & V \\ I_{o} &=& 6 & mA \\ P_{o} &=& 8 & mW \\ \hline & Characteristic line: \end{array}$		
Exia	U <sub>0</sub> = 5.9 V I <sub>0</sub> = 6 mA P <sub>0</sub> = 8 mW Characteristic line:	linear IIC	
Ex ia max. permissible external inductance max. permissible external capacitance	U <sub>0</sub> = 5.9 V I <sub>0</sub> = 6 mA P <sub>0</sub> = 8 mW Characteristic line:	linear	5000 μH 2100 nF
max. permissible external inductance	U <sub>o</sub> = 5.9 V I <sub>o</sub> = 6 mA P <sub>o</sub> = 8 mW Characteristic line: 20000 µH 1800 nF	linear IIC 10000 µH 1900 nF	2100 nF
max, permissible external inductance max, permissible external capacitance Pressure sensor circuit, internal	$\begin{array}{rcl} U_{o} &= 5.9 & V \\ I_{o} &= 6 & mA \\ P_{o} &= 8 & mW \\ \hline & & \\ Characteristic line: \\ \hline & \\ \hline & \\ 20000 \ \mu H \\ \hline & \\ 1800 \ nF \\ \hline \\ \hline & \\ 1800 \ nF \\ \hline \\ \hline & \\ n \ type \ of \ protection \\ Maximum \ values: \\ U_{o} &= 5.9 V \\ I_{o} &= 100 \ mA \\ P_{o} &= 148 \ mW \end{array}$	linear IIC 10000 µH 1900 nF	2100 nF
max. permissible external inductance max. permissible external capacitance Pressure sensor circuit, internal (Terminals X8; 1 4)	$\begin{array}{rcl} U_{o} &= 5.9 & V \\ I_{o} &= 6 & mA \\ P_{o} &= 8 & mW \\ \hline & & \\ Characteristic line: \\ \hline & \\ \hline & \\ 20000 \ \mu H \\ \hline & \\ 1800 \ nF \\ \hline \\ \hline & \\ 1800 \ nF \\ \hline \\ \hline & \\ n \ type \ of \ protection \\ Maximum \ values: \\ U_{o} &= 5.9 V \\ I_{o} &= 100 \ mA \\ P_{o} &= 148 \ mW \end{array}$	linear IIC 10000 µH 1900 nF n Intrinsic Sat	2100 nF



RMG











-27		
1	Proc	luction Quality Assurance
		Notification
2	Equipment and Protective Systems intended for use in potentially explosive atmospheres Directive 2014/34/EU Annex IV - Module D: Conformity to type based on quality assurance of the production process Annex VII - Module E: Conformity to type based on product quality assurance	
3	Notification number	
4	Product category:	Equipment and components equipment-group II, category 2G: Manufacturing and sale of Volume Meters, Electronic Correctors and Gas Analysers, Electrical equipment and devices
		RMG
5	Manufacturer:	RMG Messtechnik GmbH
6	Address:	Otto-Hahn-Straße 5, 35510 Butzbach, Germany
	Site(s) of	Otto-Hahn-Straße 5, 35510 Butzbech, Germany
	manufacture:	RMG Messtechnik GmbH, Heinrich-Lanz-Straße 9, 67259 Beindersheim, Germany
7	The certification body of DEKRA EXAM GmbH, Notified Body No 0158 in accordance with Article 17 of the Council Directive 2014/34/EU of 26 February 2014 notifies that the manufacturer has a production quality system, which complies with Annex IV of the Directive. This quality system in compliance with Annex IV of the Directive also meets the requirements of Annex VII. In the updated annex all products covered by this notification and their type examination certificate numbers are listed.	
8	This notification is based on audit report ZQS/E139/17 issued 2017-10-24. Results of periodical re-assessments of the quality system are a part of this notification.	
9	This notification is valid from 2017-10-28 until 2020-10-28 and can be withdrawn if the manufacturer does not satisfy the production quality assurance surveillance according to Annex IV and VII.	
10	According to Article 16 (3) of the Directive 2014/34/EU the CE marking shall be followed by the identification number 0158 of DEKRA EXAM GmbH as notified body involved in the production control phase.	
	DEKRA EXAM Gm Bochum, 2017-10-2	
	1000	Certifier Approver
		This is a translation from the German original. In the case of arbitration only the German working shall be valid and binding.
	DEKRA EXAM Gmb	Page 1 of 1 This notification may only be reproduced in its entirety and without any change. I Dimendahistrasse 9 44809 Bochum Germany Phone +49.234.3696-105 Fax +49.234.3696-110 e-mail zs-exam@dekra.com



### Contact

### **RMG Messtechnik GmbH**

Otto-Hahn-Straße 5

35510 Butzbach, Deutschland

Tel: +49 (0) 6033 897 - 0

Fax: +49 (0) 6033 897 - 130

### RMG 中国地区代理商



https://www.safedtech.com

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联系人: 刘 先生 18688194199

